

Overview of Weather and Network Path Modeling in Support of CDM Work at Virginia Tech

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Project Goals

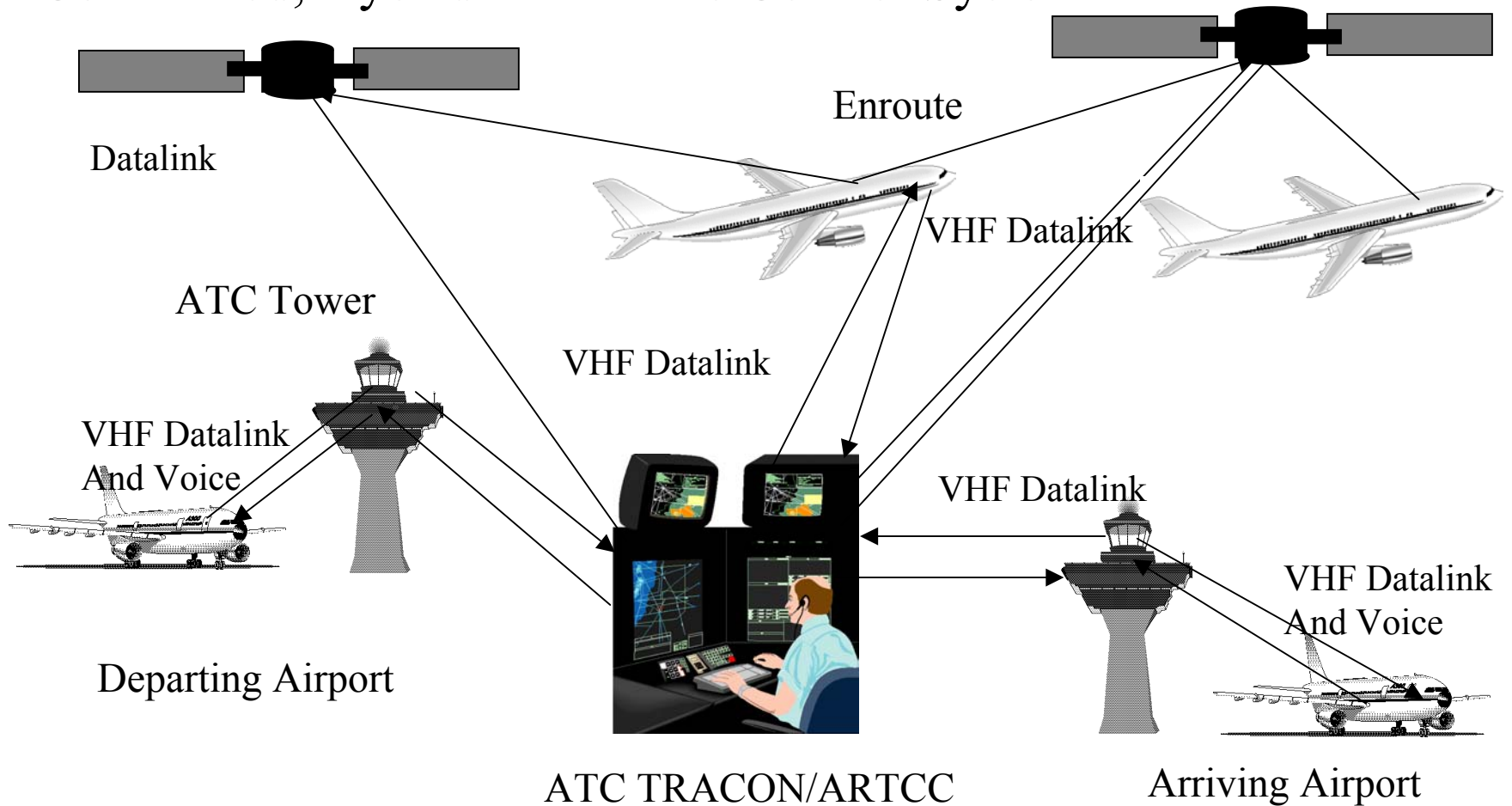
- To develop optimization and simulation-based techniques to manage air traffic in the en-route airspace
- The techniques developed in this project consider realistic air traffic management constraints (weather, safety, sector workloads, airline equity, and aircraft performance among others)

Potential Research Impacts

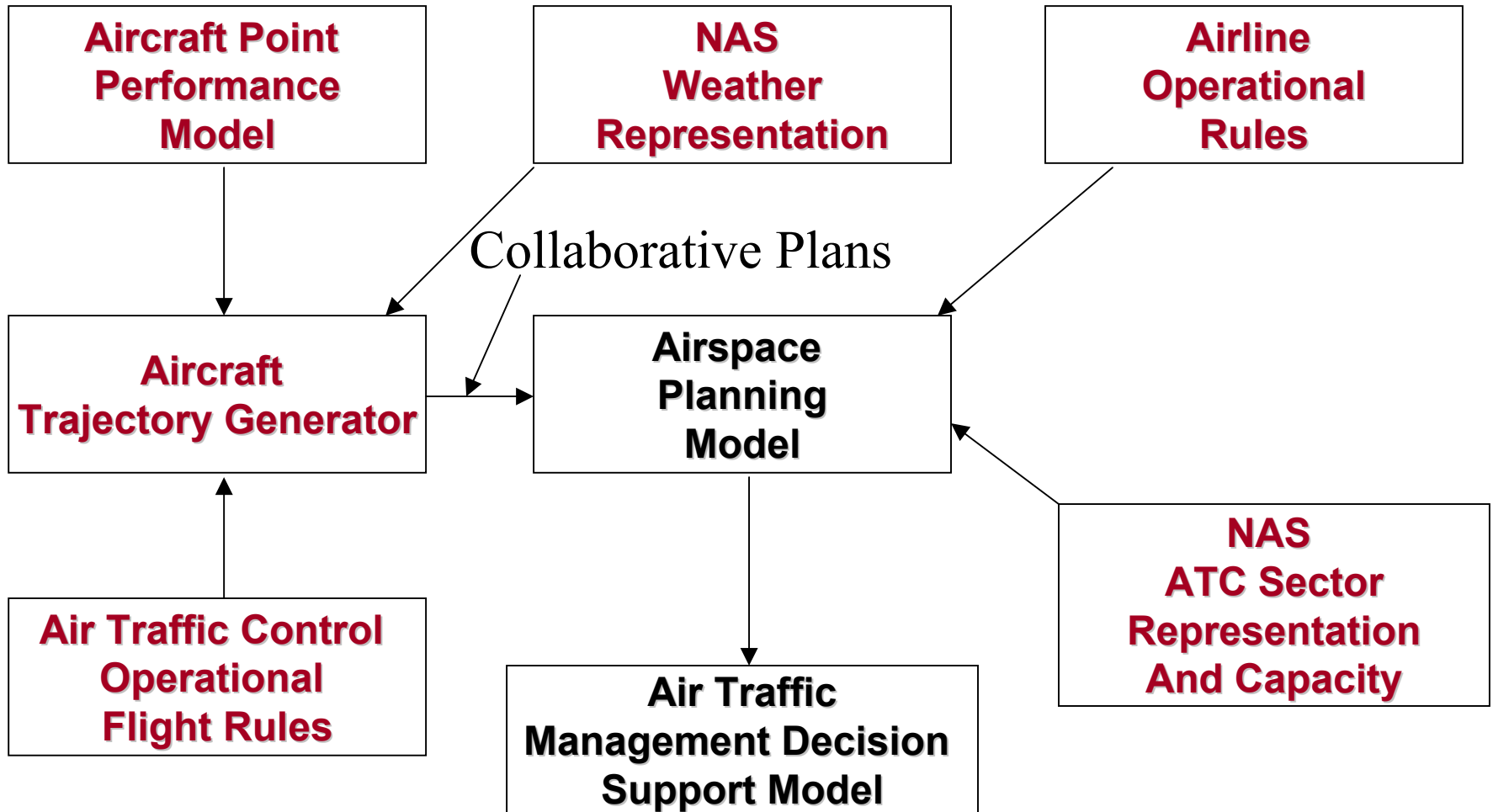
- Long-term outlook for air transportation services will continue to increase at 1-3% per year
- Delays in the National Airspace System (NAS) continue to grow (due to demand concentration at airport hubs)
- Last year, the cost of delays in NAS was estimated at 3 billion dollars
- The application of advanced methods in air traffic management can produce small/moderate increases in supply

Future NAS ATC/ATM System

Centralized, Hybrid Air Traffic Control System



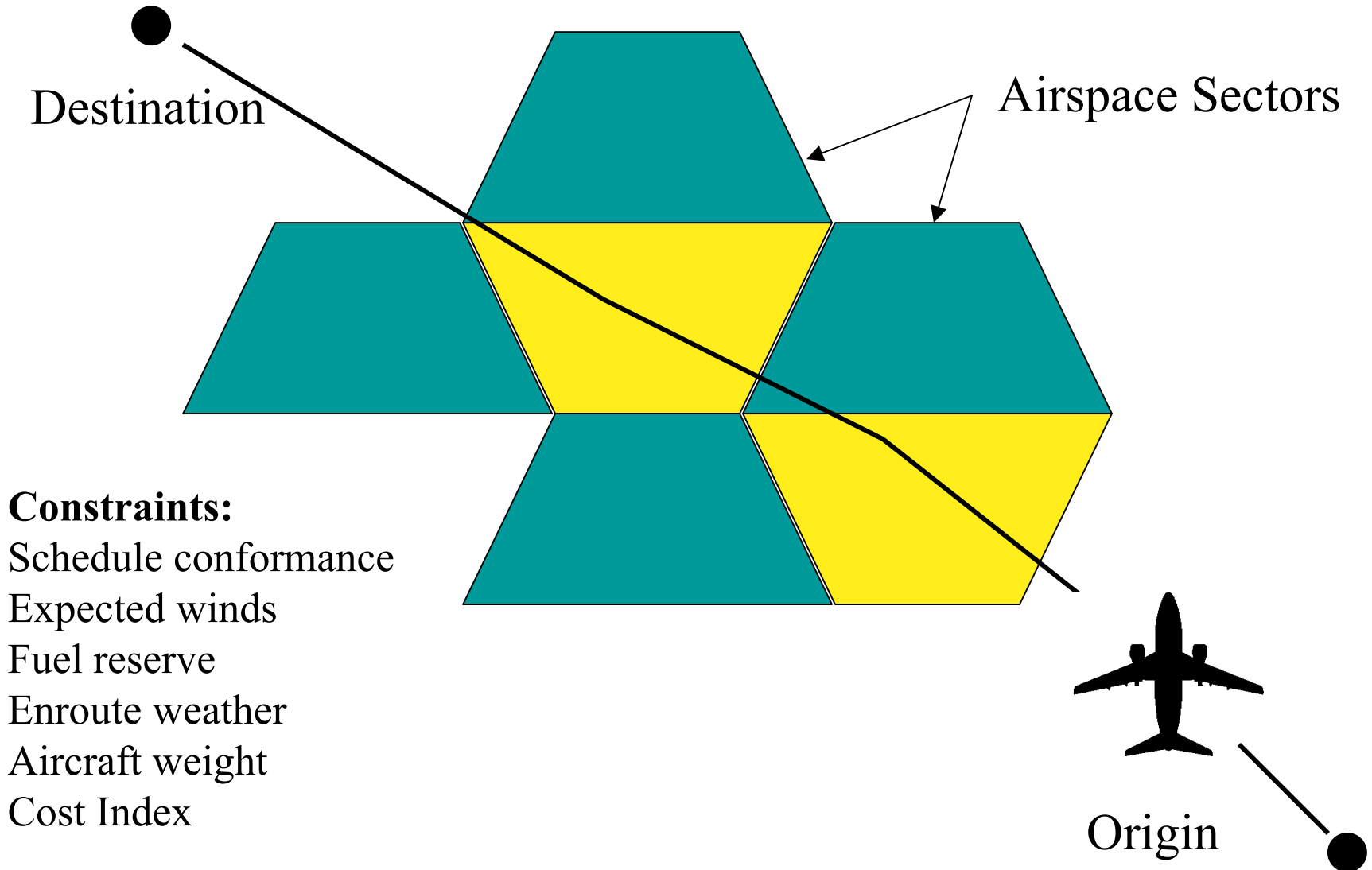
Approach to the Enroute Air Traffic Management Problem



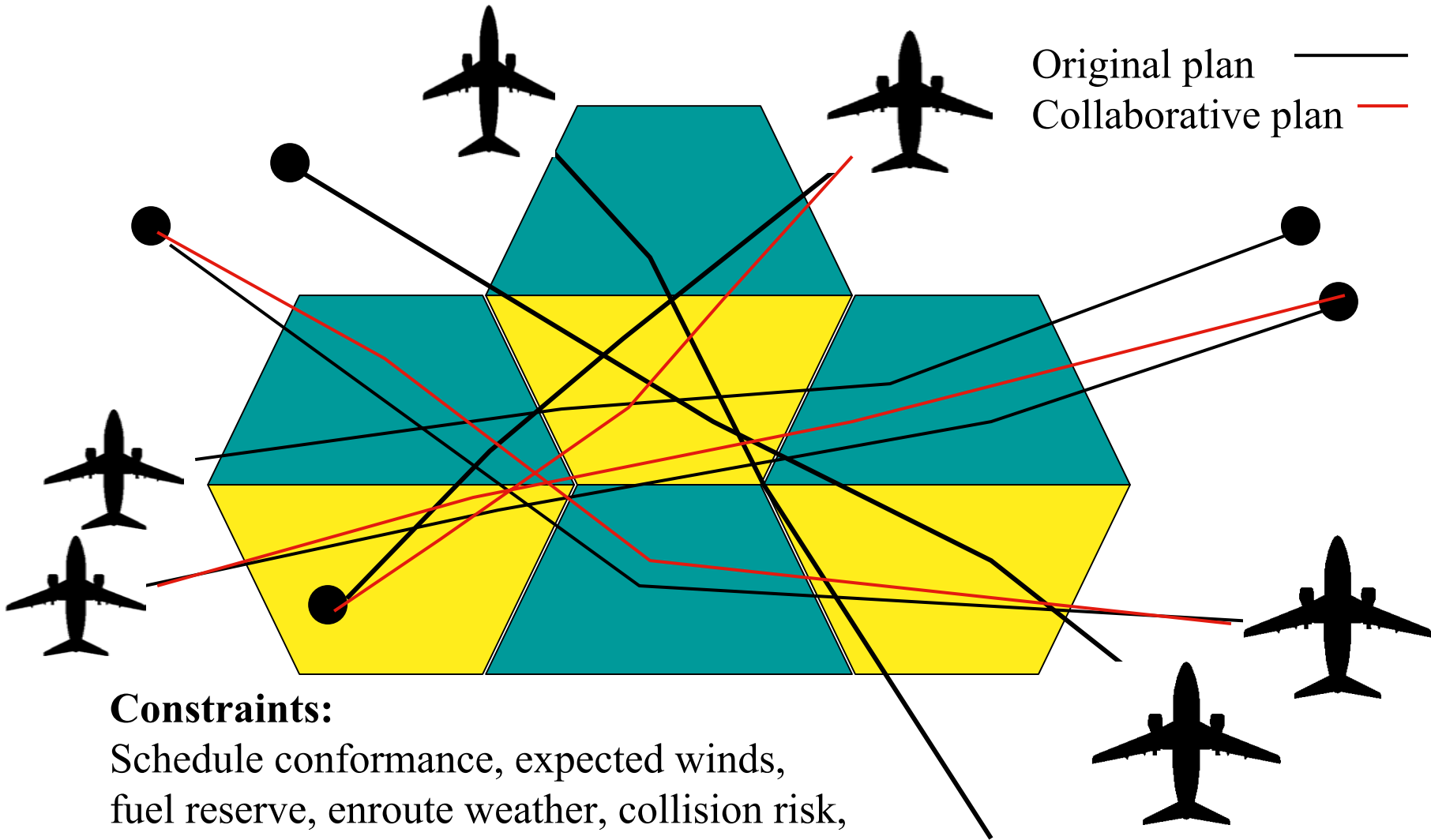
Enroute Selection Modeling

- Route selection in the context of a highly constrained airspace is a large, complex systems problem.
- The simultaneous selection of a set of routes that achieves system-wide objectives can have a combinatorially large set of alternatives.

Single Route Optimization



Collaborative Routing



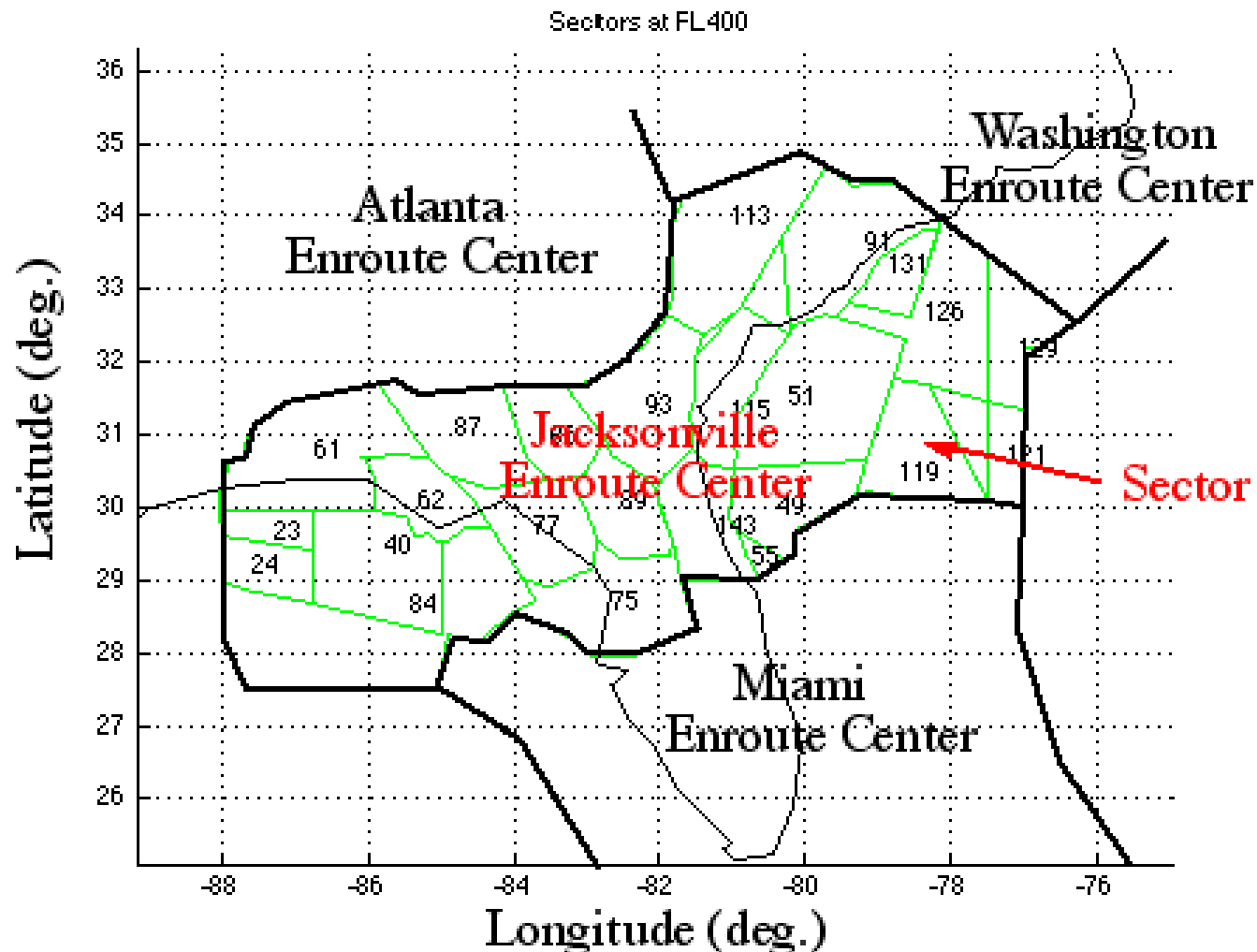
Constraints:

Schedule conformance, expected winds,
fuel reserve, enroute weather, collision risk,
aircraft weight, sector workload, cost index

Route Selection Models (Development issues)

- Consideration of rationing schemes and CDM principles
- Software implementation and integration into TFM tools
- Incorporate collaborative airline-FAA route development strategies
- Consideration of realistic airspace sector capacity limitations
- Consideration of collision risk and safety issues

Airspace Sector Partitions

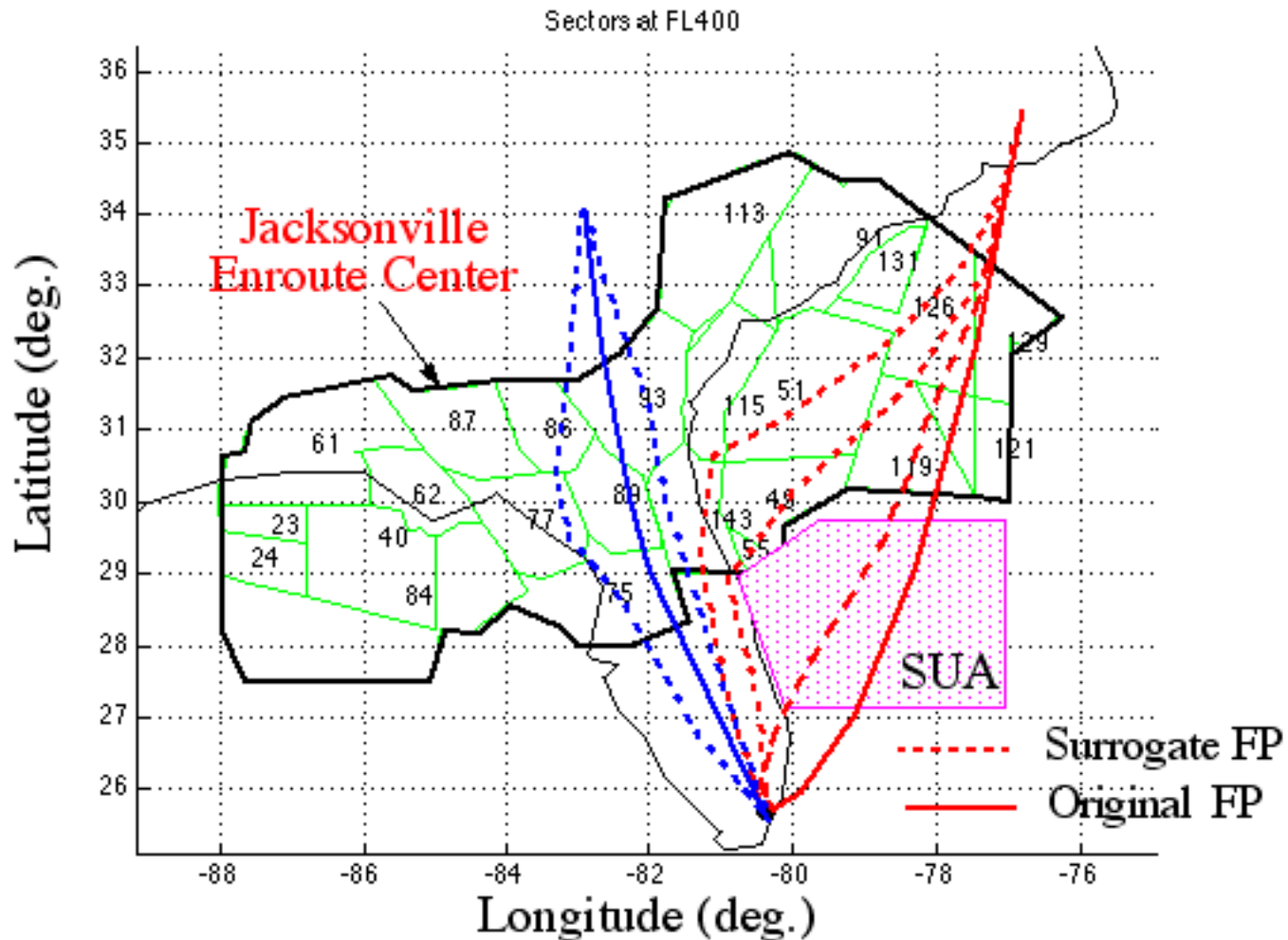


An Airspace Planning Model (APM)

- Examines a finite rolling planning horizon
- Considers a set of flight plans covering this horizon that are relevant to interactions with a particular SUA or weather system event
- Minimizes the total fuel and delay cost while prescribing a set of flight plans to be adopted
- Reflects flight plan cost index, delay costs, sector capacity, collision risk, and airline equity
- Models uncertainties in flight trajectories

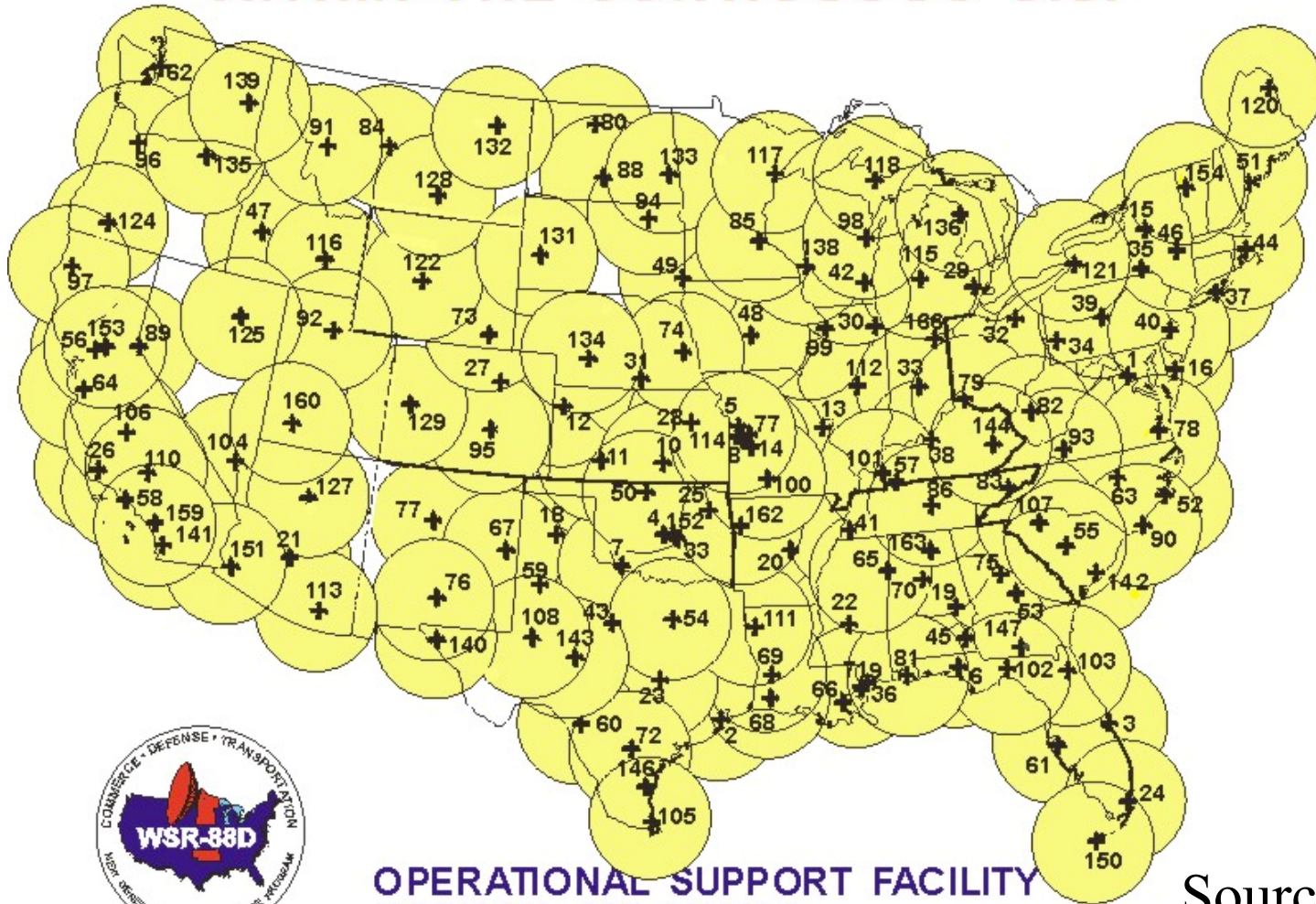
NOTE: Model will be described in a separate presentation by VT

Graphical Interpretation of APM



Weather Data Sources

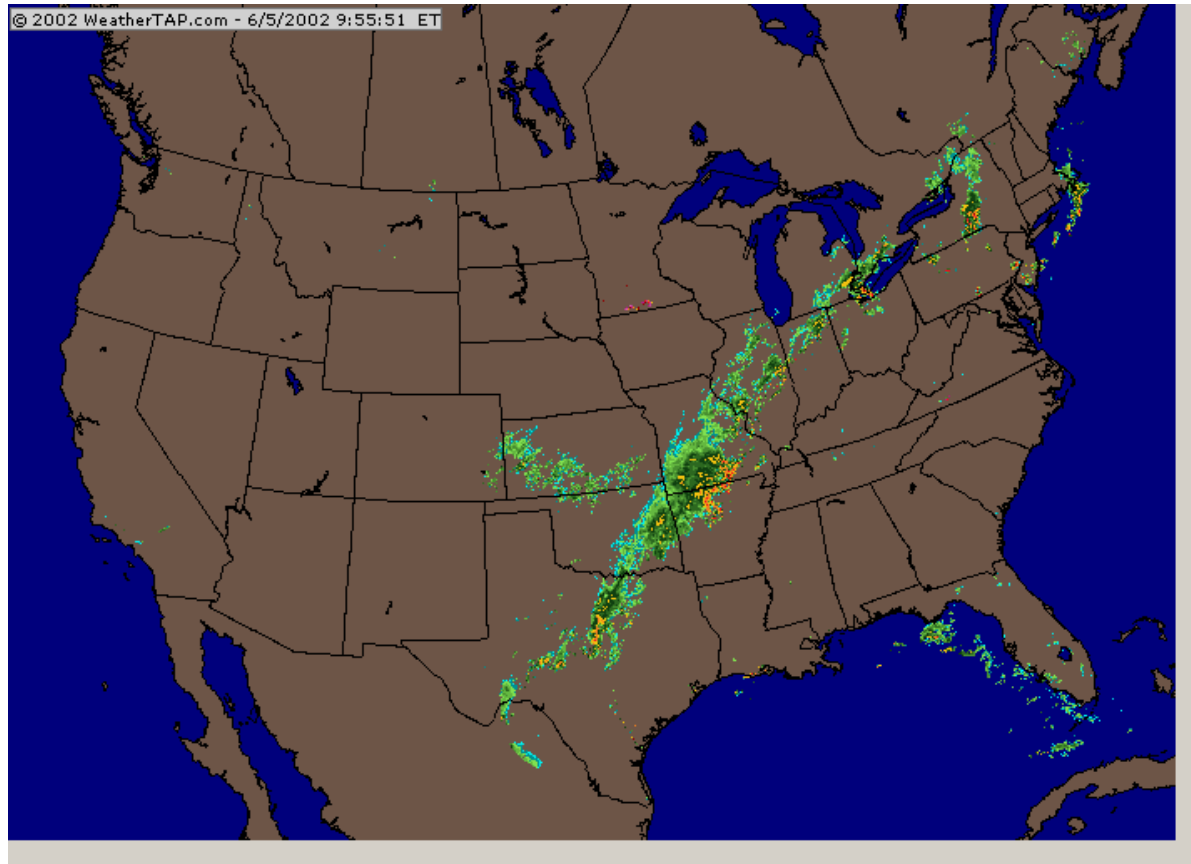
COMPLETED WSR-88D INSTALLATIONS WITHIN THE CONTIGUOUS U.S.



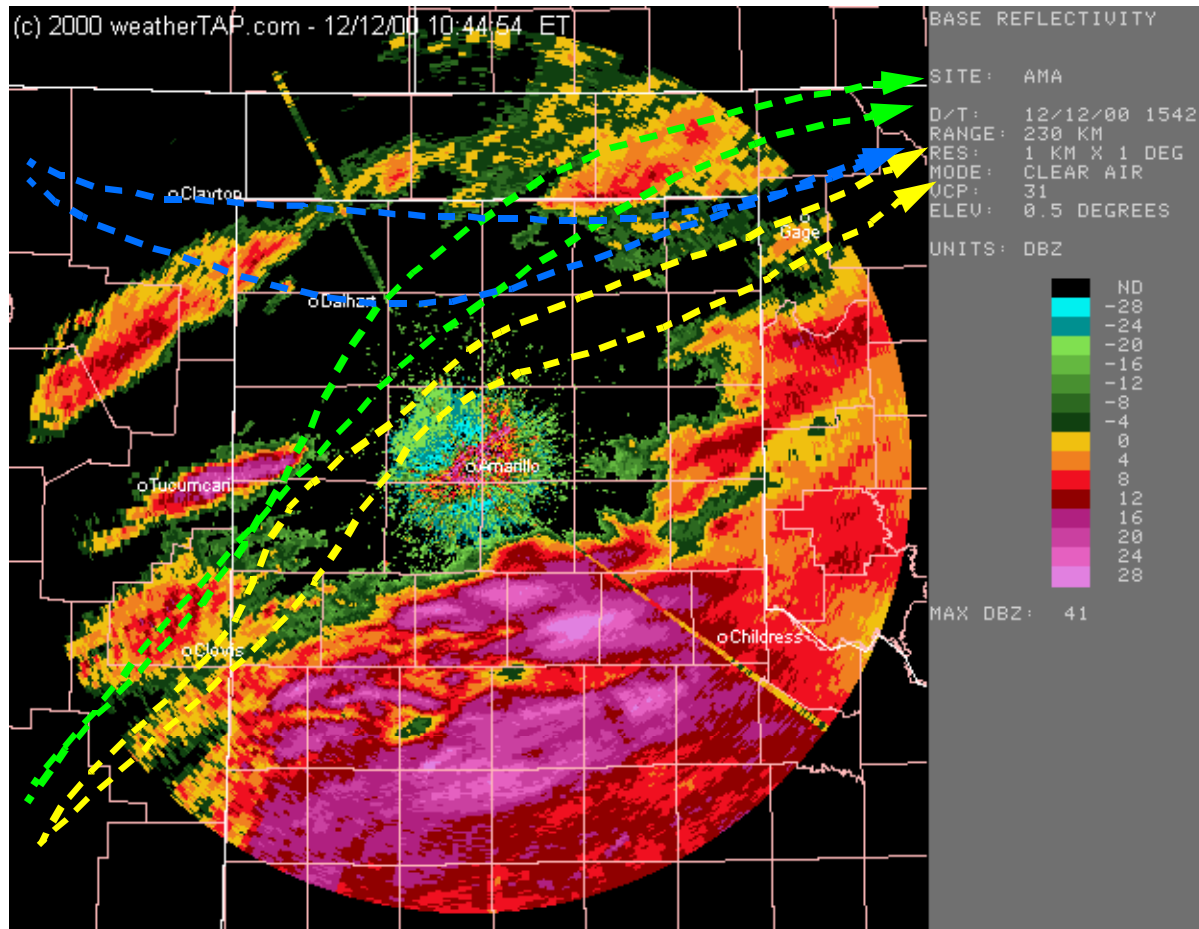
OPERATIONAL SUPPORT FACILITY
NORMAN, OKLAHOMA

Source: NWS

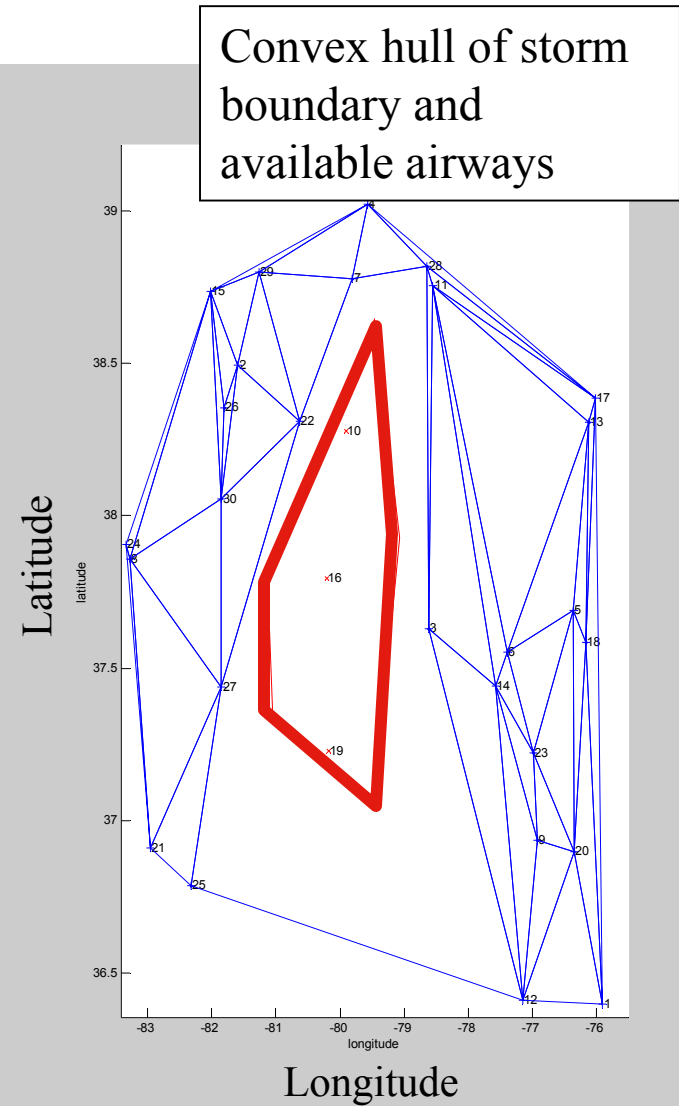
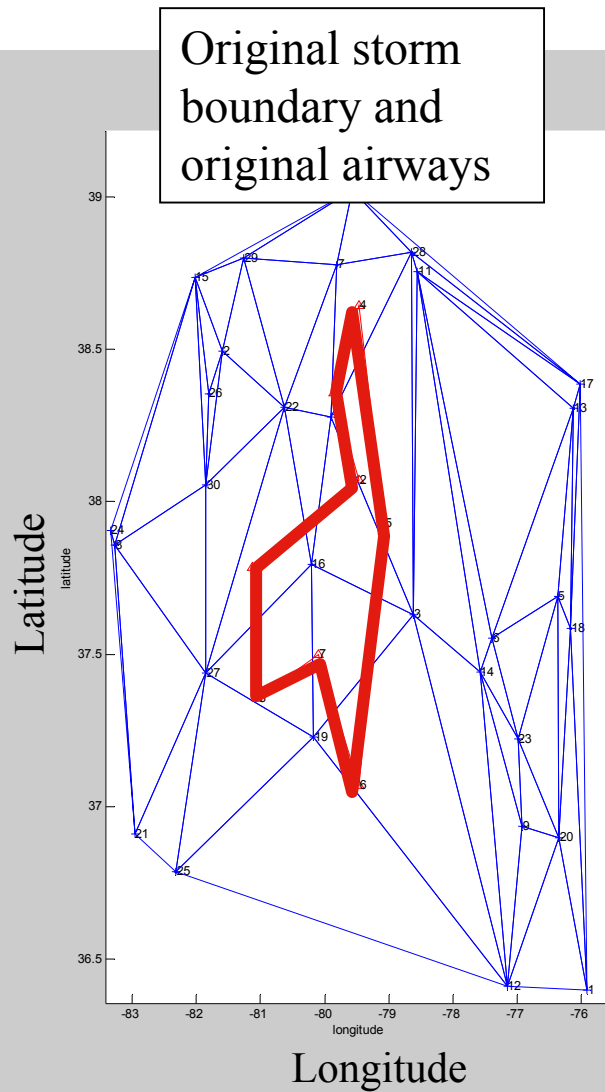
Weather Data (National Mosaic)



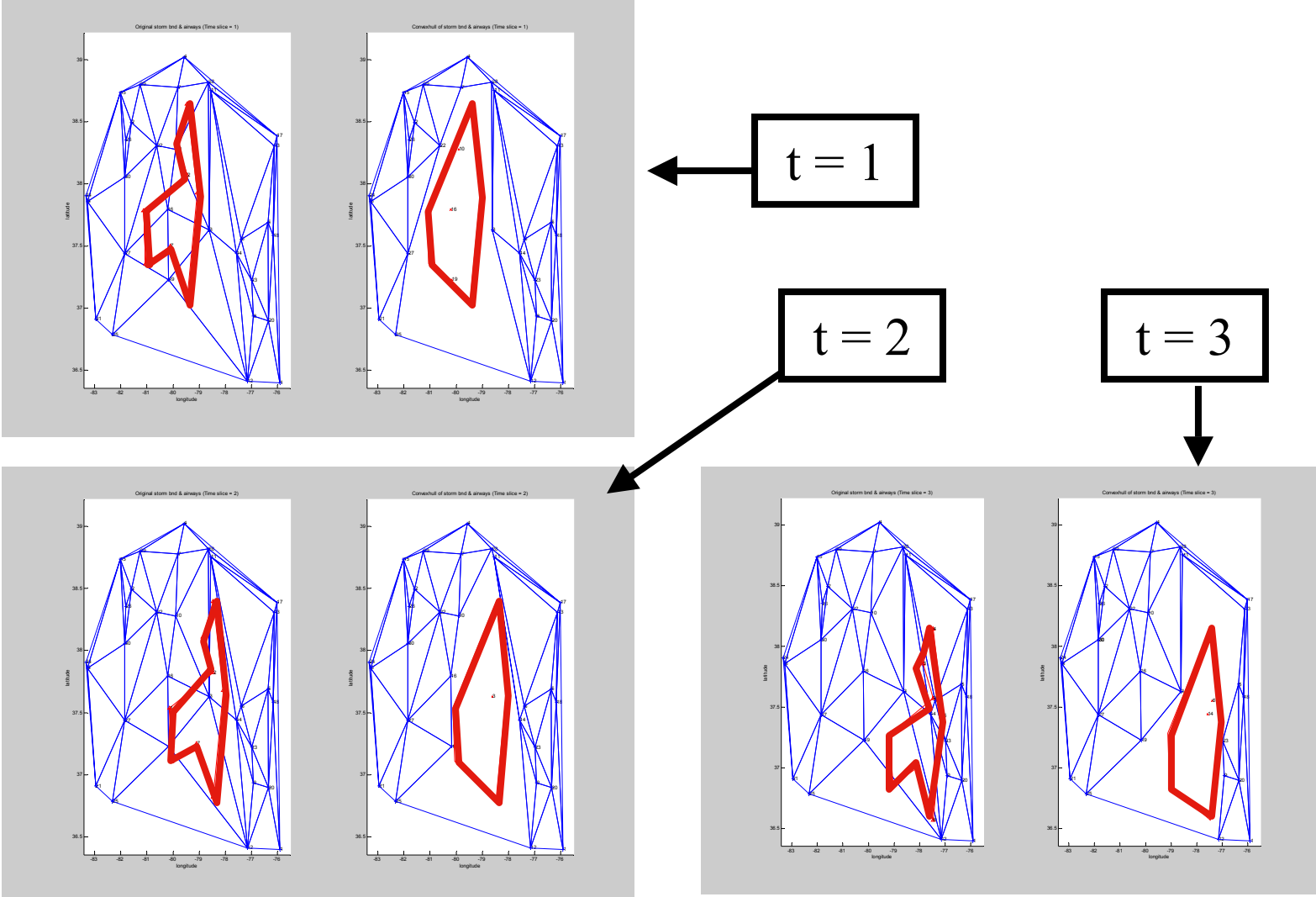
Weather Data (Example)



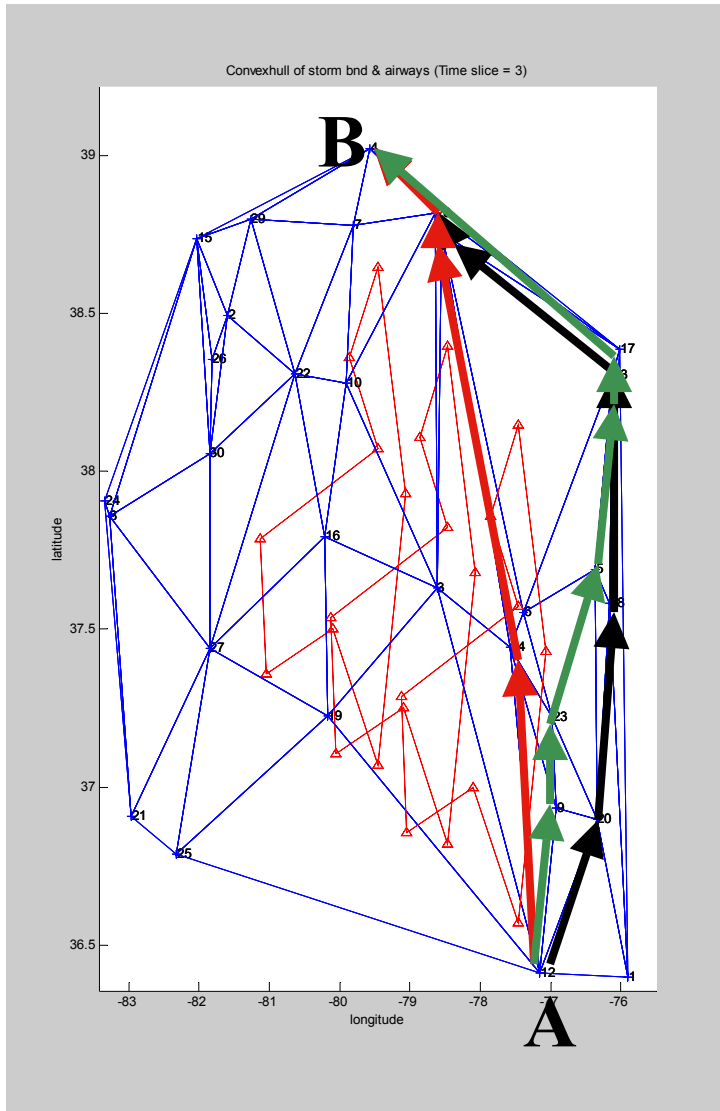
Flight Path Modeling with Severe Weather



Flight Path Modeling with Severe Weather



Routes From A to B (Airbus300, FL300)



→ Static Path

Distance: 151 nm
Travel Time: 19.7 min
Fuel: 1942 kg

→ Time-Dep. Path (1)

Distance: 282 nm
Travel Time: 37.8 min
Fuel: 3619 kg

→ Time-Dep. Path (2)

Distance: 296 nm
Travel Time: 38.7 min
Fuel: 3808 kg

Computational Issues

- Adopt time-dependent shortest path (TDSP) algorithm with double-ended queue (DeQue) data structure.
- Adopt Eurocontrol's BADA 3.3 aircraft performance model.

TDSP Algorithm

Call **Initialize**

```
while(SE list is not empty){
    u = Call deQueue;
    d_u = Label(r, u); // arrival travel at node u starting from r at time t.
    Compute timeSlice_d_u; // compute the time slice corresponding to d_u.
    for(v = all forward star of u){
        d_v = Label(r, v); // travel time from r to v.
        l_uv = Find travelTime(u, v, timeSlice_d_u) // find the travel time for link (u,v) at timeSlice_d_u
        if(d_v > d_u + l_uv){
            Label(r, v) = d_u + l_uv; // update travel time from r to v
            Predecessor(v) = u; // update predecessor node for node v
            Call enQueue(v);
        }
    } //end for
} // end while
```

Procedure **Initialize**:

```
for (j = all nodes){
    predecessor(j) = 0;
    if(j ≠ r) Label(r, j) = infinite;
}
Label(r, r) = t;
Predecessor(r) = r;
enQueue(r);
```

Procedure **deQueue**:

```
// find the closest node from the
candidate nodes set (i.e., SE list) using
the quick-sort algorithm.
```

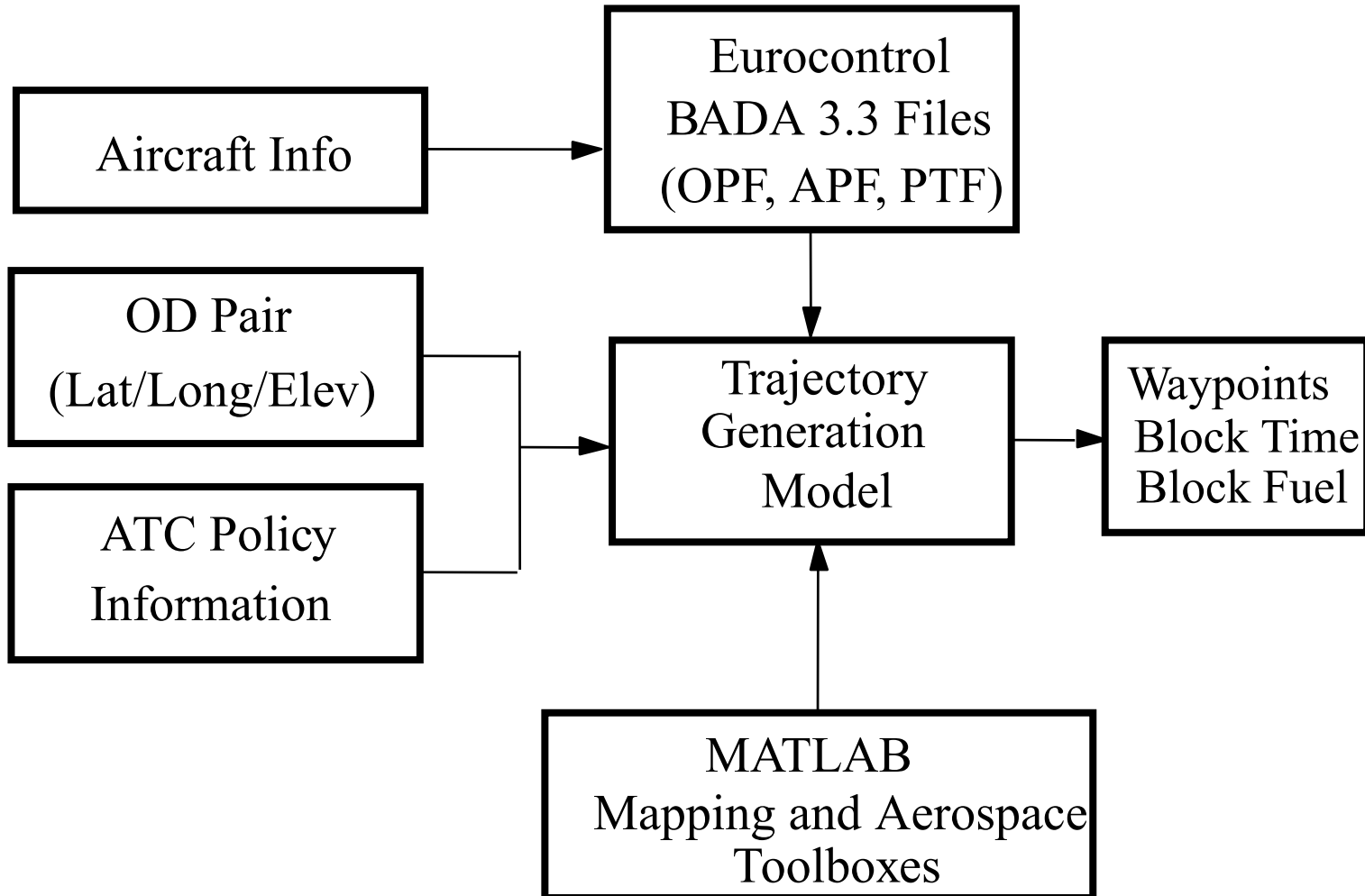
Procedure **enQueue**(x):

```
// insert node x into the candidate
nodes set (i.e., SE list).
```

BADA Model

- The cost of flight detours is a multi-attribute problem:
 - Travel time
 - Fuel cost
- Use Eurocontrol's the Base of Aircraft Data 3.3 (BADA, Dec. 2000)

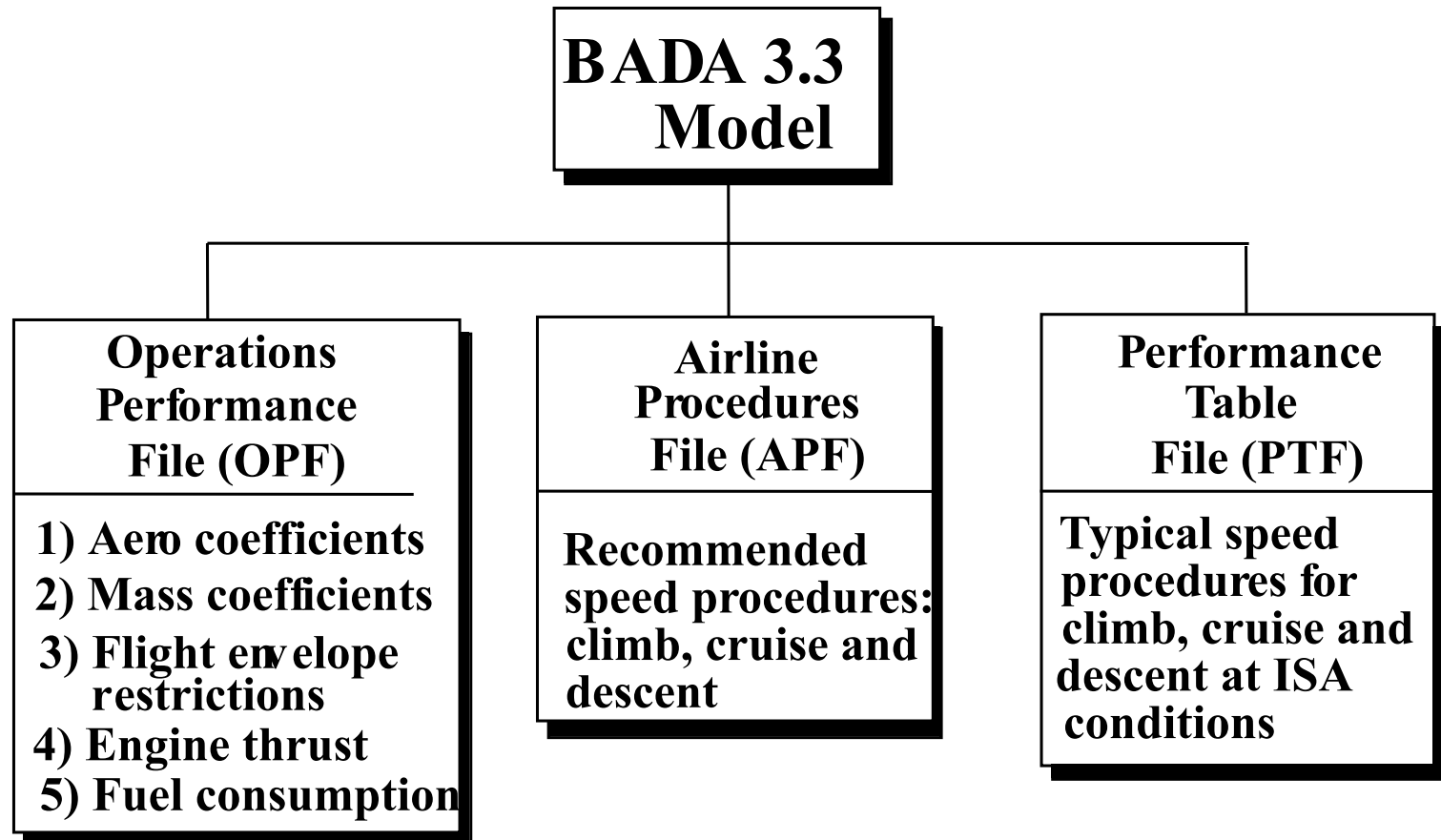
Using BADA Model



BADA Model (Detail)

- Developed by Eurocontrol Experimental Centre (ECC) to model various Air Traffic Management (ATM) concepts
 - 186 aircraft supported in BADA 3.3
 - 84 aircraft models are supported directly
 - 102 aircraft models are supported indirectly (equivalent models)
- Main outputs of the models are fuel consumption, aerodynamic and speed procedure parameters

BADA Model (Detail)



Operations Performance File (OPF)

```

CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC A320__.OPF CCCCCCCCCCCCCCCC/
CC
CC          AIRCRAFT PERFORMANCE
CC          operational    files
CC
CC      BADA RCS File Id
CC      File Name          Current Revision      Last Modification
CC                          revision    date      revision    date
CC      A320__.OPF        3.0    98/03/12    2.6.1.1    98/03/11
CC
CC      BADA Revision:
CD      Rev 3.0
CC===== Actype =====/
CD      A320                2 engines    Jet                M
CC      Airbus A320-111 with CFM56 5 A1 engines                wake
CC                          (source: AIR_FRANCE OPS manual)
CC===== Mass (t) =====/
CC      reference    minimum    maximum    max payload    mass grad
CD      .62000E+02    .41800E+02    .73500E+02    .19220E+02    .32000E+00
CC===== Flight envelope =====/
CC      VMO(KCAS)    MMO    Max.Alt    Hmax    temp grad
CD      .35000E+03    .82000E+00    .39000E+05    .36500E+05    -.40000E+02
CC===== Aerodynamics =====/
CC Wing Area and Buffet coefficients (SIM)
CCndrst Surf(m2)    Clbo(M=0)    k    CM16
CD 5    .12240E+03    .12100E+01    .47000E+00    .00000E+00
CC Configuration characteristics
CC n Phase Name    Vstall(KCAS)    CD0    CD2    unused
CD 1 CR    Clean    .14700E+03    .20000E-01    .40000E-01    .00000E+00
CD 2 IC    1+F    .11700E+03    .00000E+00    .00000E+00    .00000E+00
CD 3 TO    1+F    .11700E+03    .00000E+00    .00000E+00    .00000E+00
CD 4 AP    2    .10900E+03    .42000E-01    .34000E-01    .00000E+00
CD 5 LD    FULL    .10500E+03    .74000E-01    .35000E-01    .00000E+00

```


Performance Table File (PTF)

BADA PERFORMANCE FILE

98/03/12

AC/Type: F28__

Last BADA Revision: 3.0

Source OPF File: 3.0

98/03/12

Source APF file: 3.0

98/03/12

Speeds: CAS (LO/HI) Mach Mass Levels [kg]
 climb - 250/270 0.65 low - 20880
 cruise - 250/300 0.70 nominal - 24000
 descent - 250/280 0.70 high - 33000

Temperature: ISA

Max Alt. [ft]: 35000

FL	CRUISE				CLIMB				DESCENT			
	TAS [kts]	fuel [kg/min]		hi	TAS [kts]	ROCD [fpm]		hi	fuel [kg/min]	TAS [kts]	ROCD [fpm]	fuel [kg/min]
		lo	nom			lo	nom		nom		nom	nom
0					127	2760	2860	2370	108.1	108	900	19.5
5					128	2710	2820	2330	106.4	108	910	19.5
10					129	2670	2780	2290	104.6	114	890	19.4
15					135	2800	2880	2360	103.3	125	850	19.4
20					136	2760	2830	2320	101.6	157	820	19.4
30	261	19.5	20.8	25.8	159	3270	3260	2650	100.0	230	1070	19.3
40	265	19.5	20.9	25.8	193	3960	3820	3070	99.3	233	1080	19.2
60	272	19.6	21.0	26.0	272	5170	4570	3410	98.3	240	1110	19.1

Mathematical Model

- BADA uses a total energy model to derive aircraft performance

$$(T - D)V = mg \frac{dh}{dt} + mV \frac{dV}{dt}$$

where: dh/dt is the rate of climb (m/s)

dV/dt is the acceleration along the flight path (m/s²)

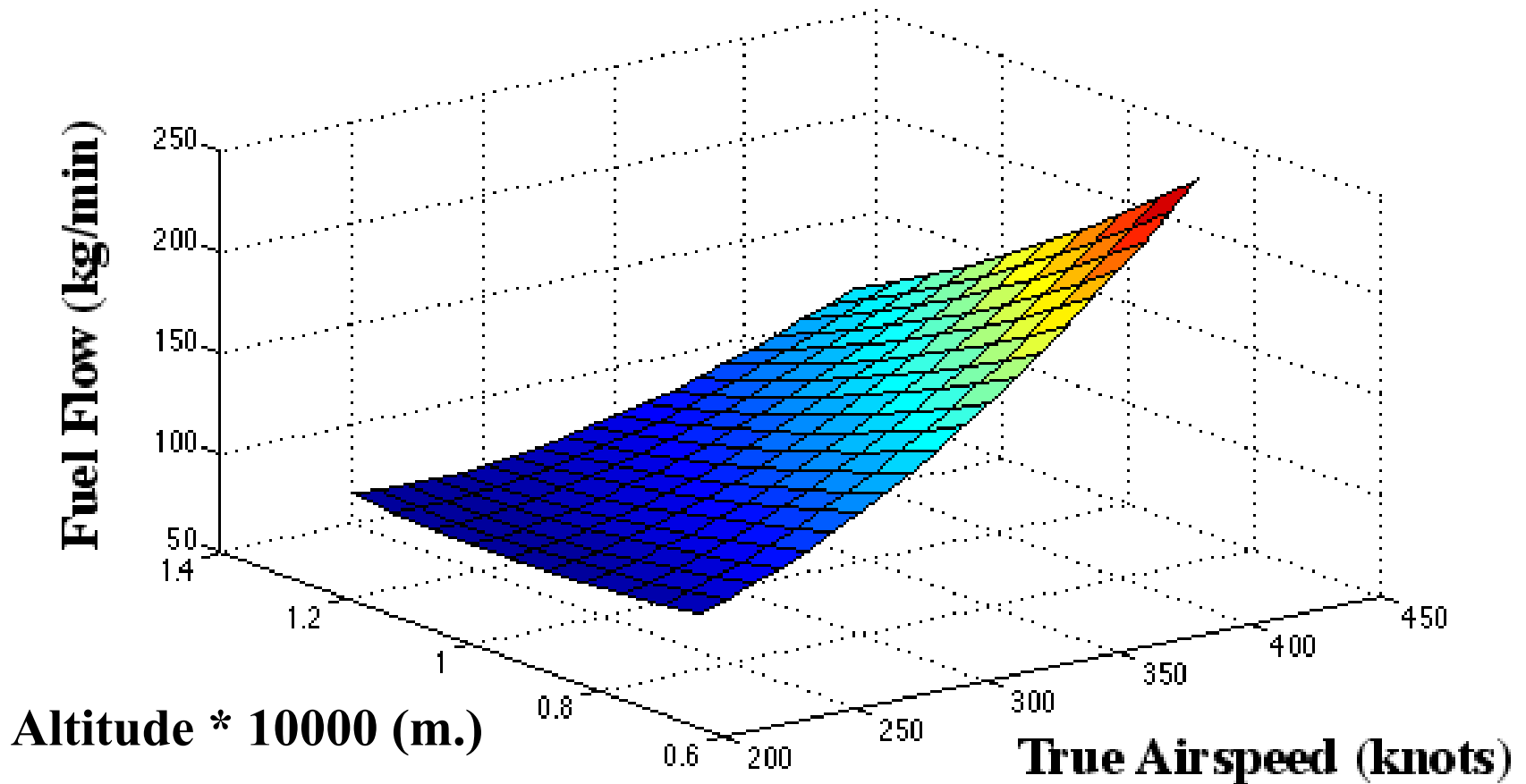
h is the aircraft altitude (m)

V is the aircraft speed (m/s)

T and D are aircraft thrust and drag (N)

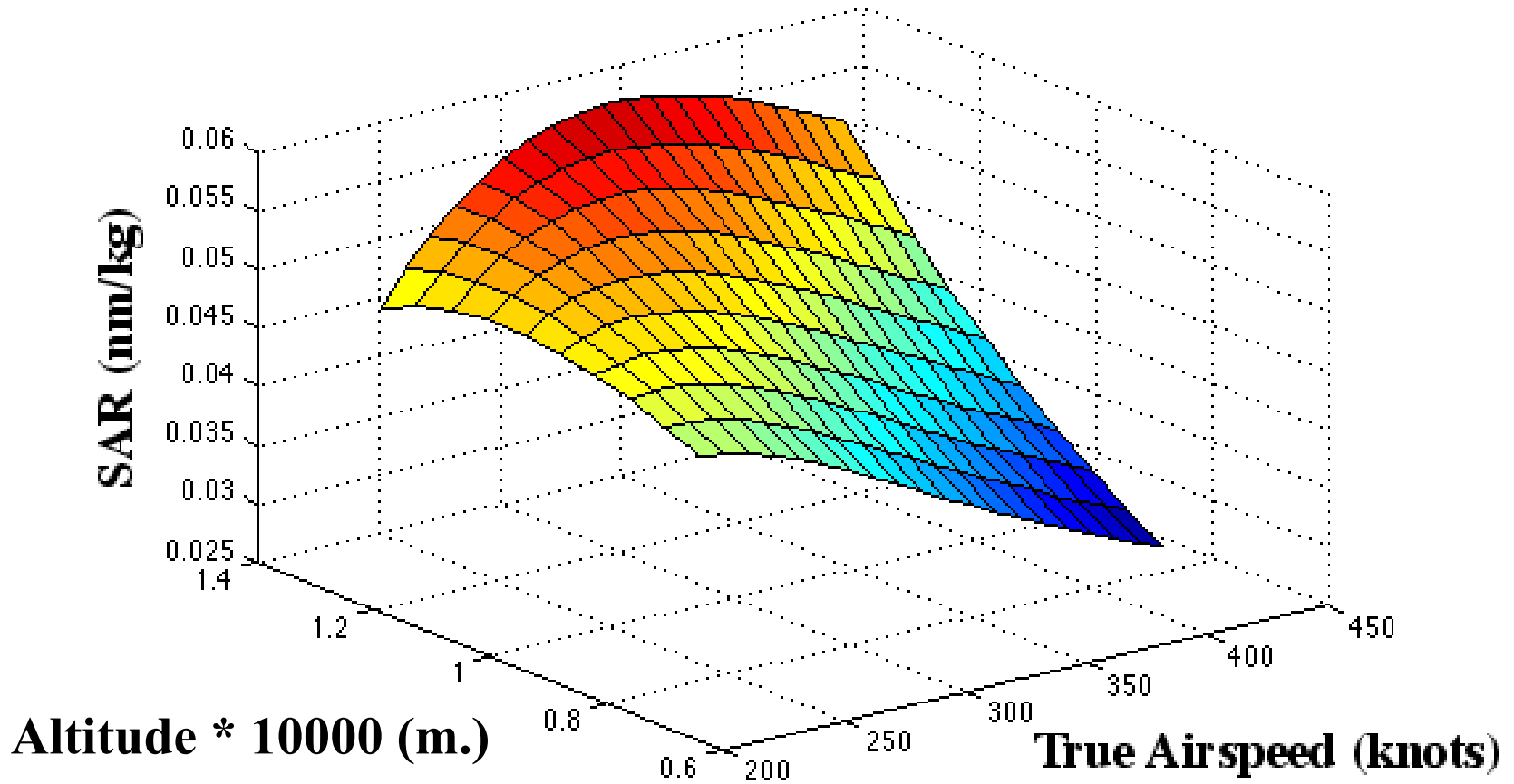
BADA Fuel Consumption Results

Airbus A300-600

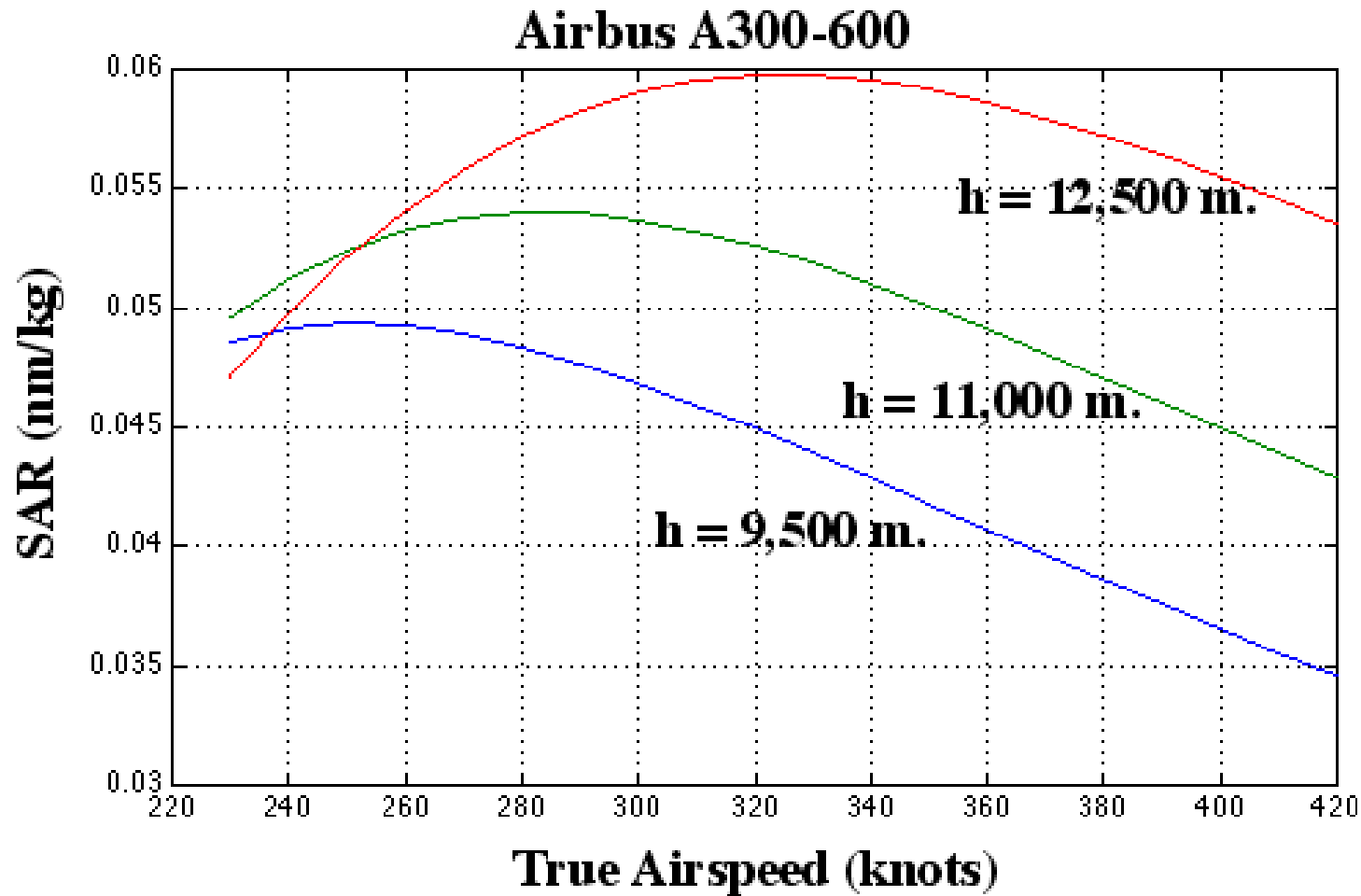


BADA Results (Specific Air Range - SAR)

Airbus A300-600



Sample BADA Results (SAR)



Mathematical Description of APM (Objective Function)

Minimize

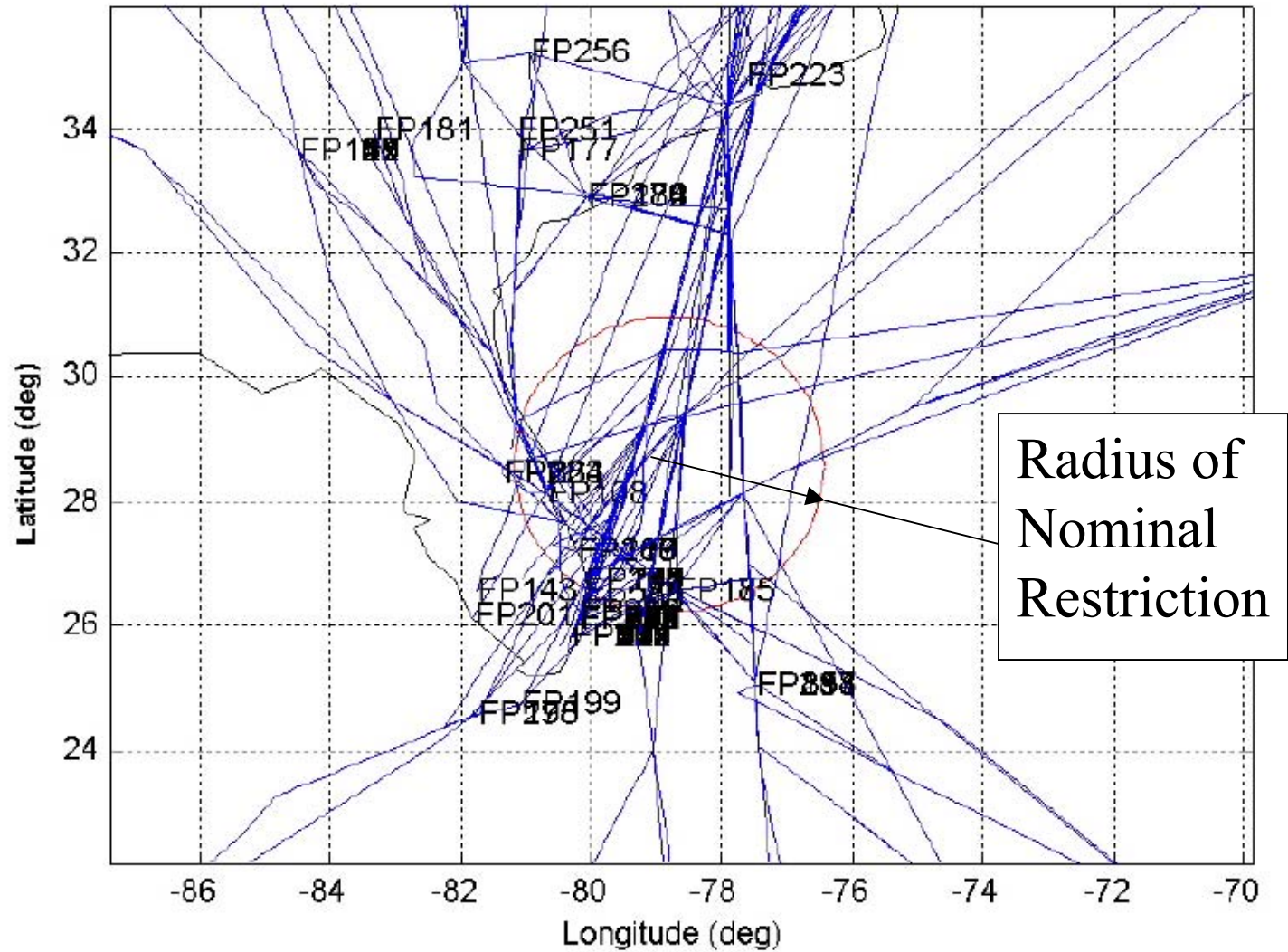
$$\sum_{i \in M} \sum_{p \in P_i} C_{ip} x_{ip} + \sum_{s \in S} \sum_{n=1}^{\bar{n}_s} \mu_{sn} y_{sn} + \mu_e (x_u^e - x_l^e) + \mu_u x_u^e$$

**Cost of adopting
A mix of flight plans**

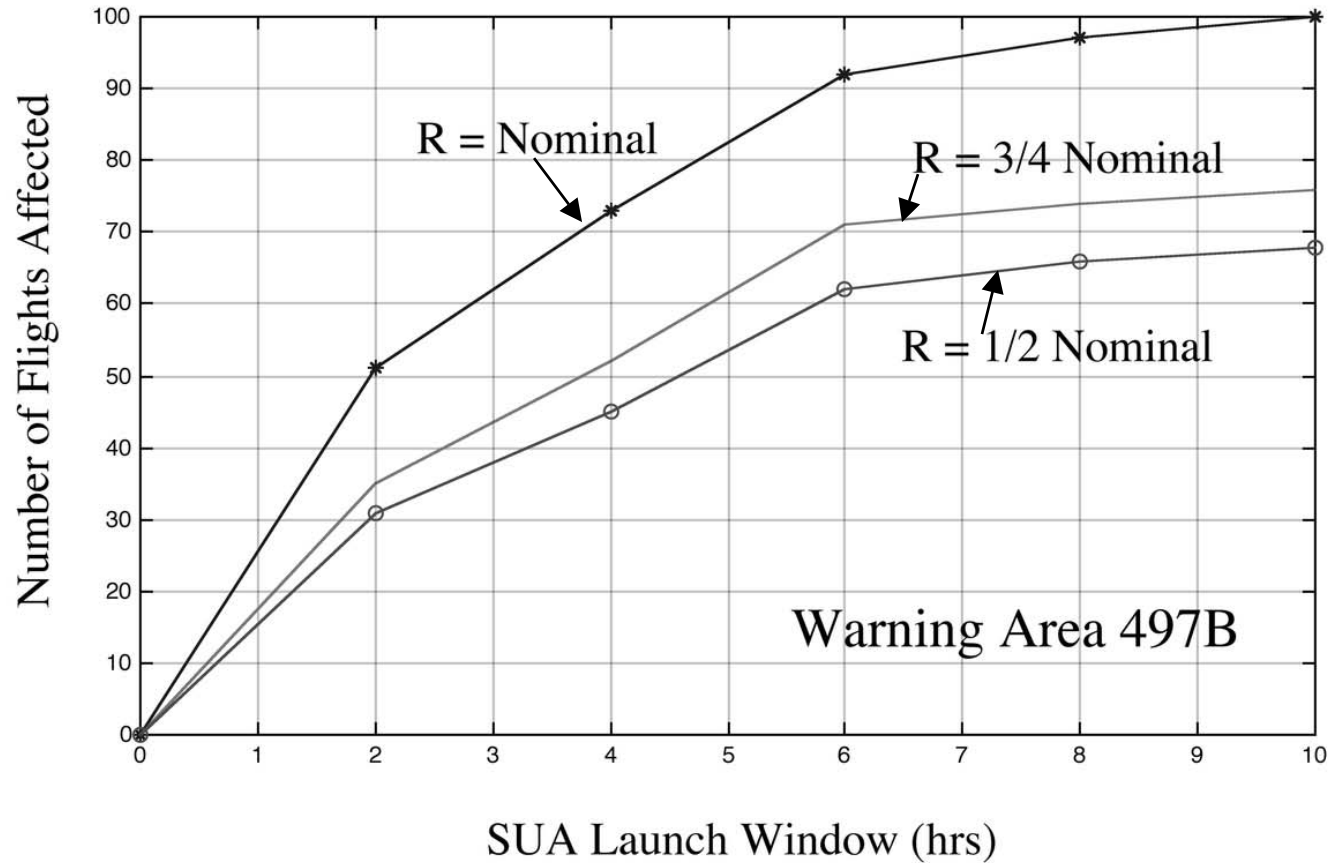
**Penalty associated
with sector load**

**Penalty to maintain
equity among airlines**

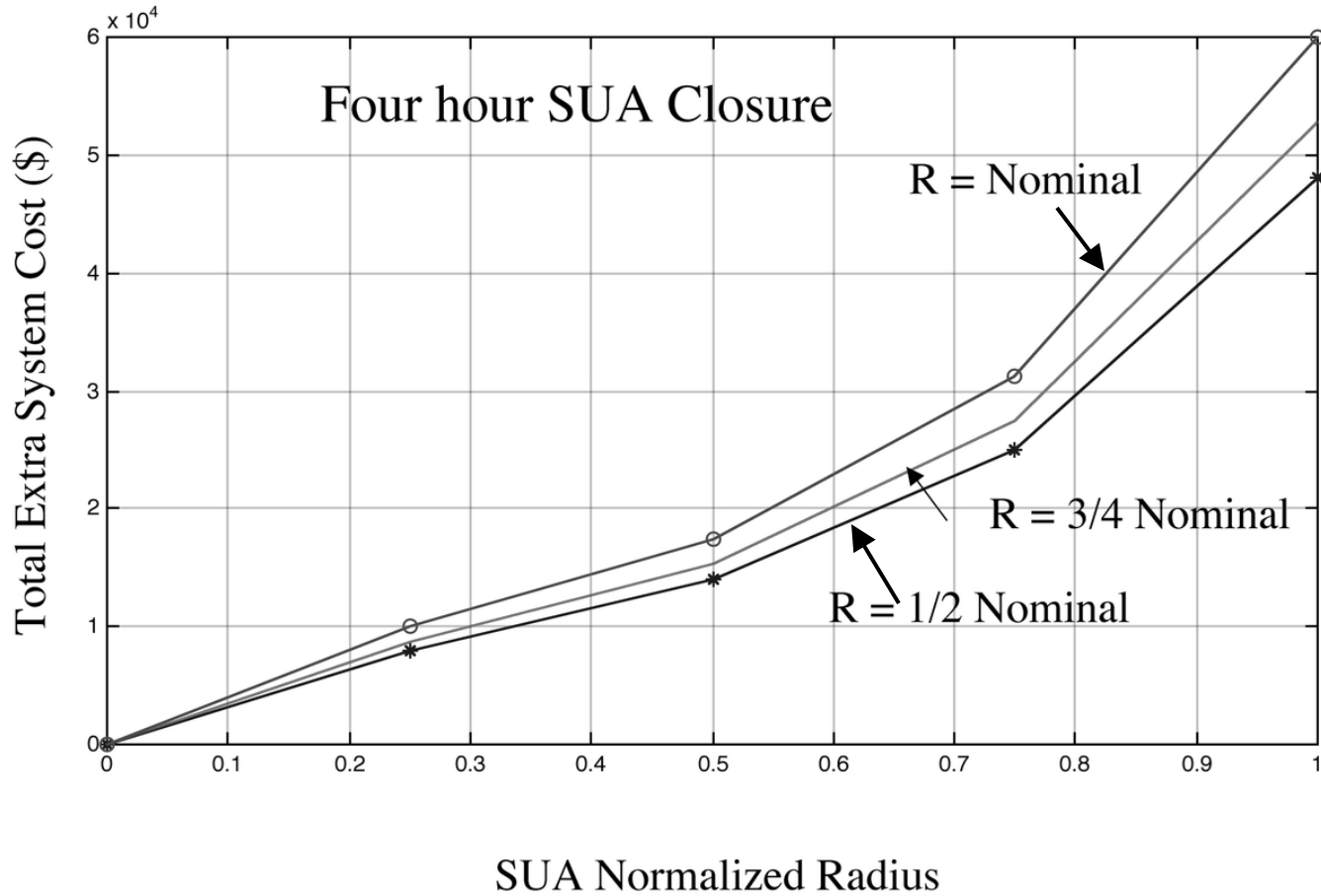
Sample Scenario



Computational Experience



Enroute Airspace Detour Costs



Critical Issues in CDM Route Model Development

- Assessment of sector capacities and workload constraints
- Modeling credible aircraft flight track uncertainty
- Definition of “good” finite surrogate flight plan sets
- Flexibility of performance indices to accommodate airline and FAA practices (system level)
- Real-time implementation issues

Research Findings

- ATM problems considering path uncertainty are very complex combinatorial optimization problems (large arrays and real-time solutions)
- RLT techniques provide some time savings to solve the problem
- Solutions obtained with APM are very dependent on the quality of the initial set of flight paths generated in the problem

Recommendations for Future Research

- Improvements to model uncertainty of the flight path is critical
- Improvements in modeling weather patterns is needed
- Better integration between ATM Decision Support Tools and weather information is needed
- The airport ground component is critical to improve the overall capacity of the National Airspace System