

UAV-Traffic Information Exchange Network

Blockchain-inspired Data Transmission Mechanism

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- What are the properties of UAV-TIEN?
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- Conclusion & Future Work

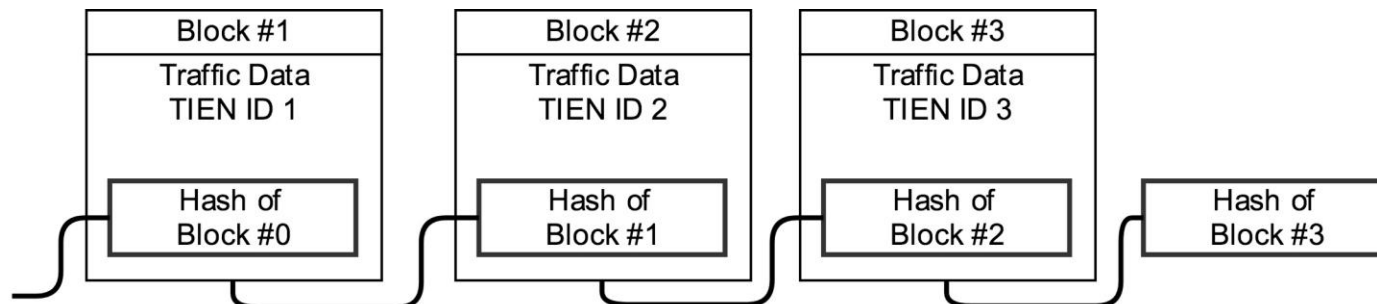
Research Motivation

- Several forecasts show the increasing demand of operations of commercial UAVs in metropolitan area in the future
- A reliable traffic data source is the fundamental assumption for all of collision avoidance algorithms but...
 - Performance of ADS-B type data transmission mechanism is shadowed in cities due to skyscrapers/obstacles
 - Distributed radar system is too expansive
 - Antenna of cellular towers are directed to ground
 - Low altitude operation is more prone to cyber-attacks
- The six requirements for an open, safe, spontaneous traffic information sharing system are:
 1. Ad-hoc network
 2. High Data Refresh Rate
 3. Secure Data Transmission
 4. Economical Data Distribution
 5. Compatible with third party detect-and-avoid systems
 6. Ability to deliver information in presence of large number of obstacles

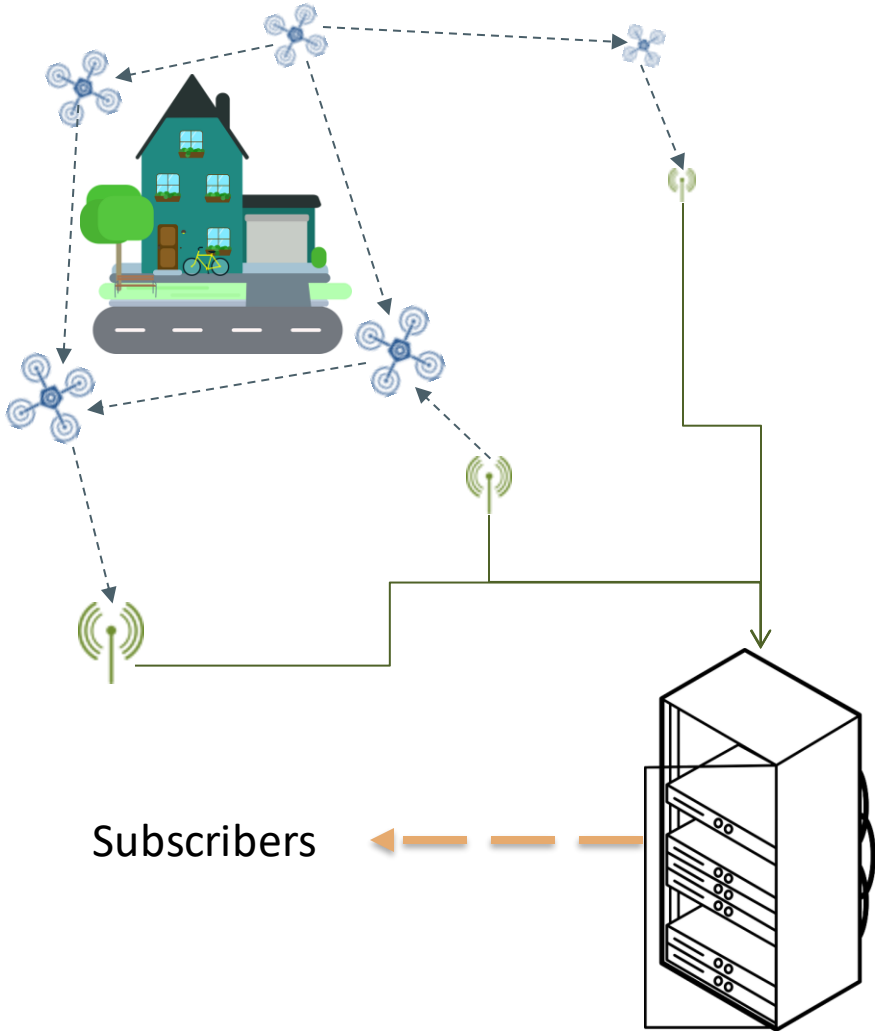
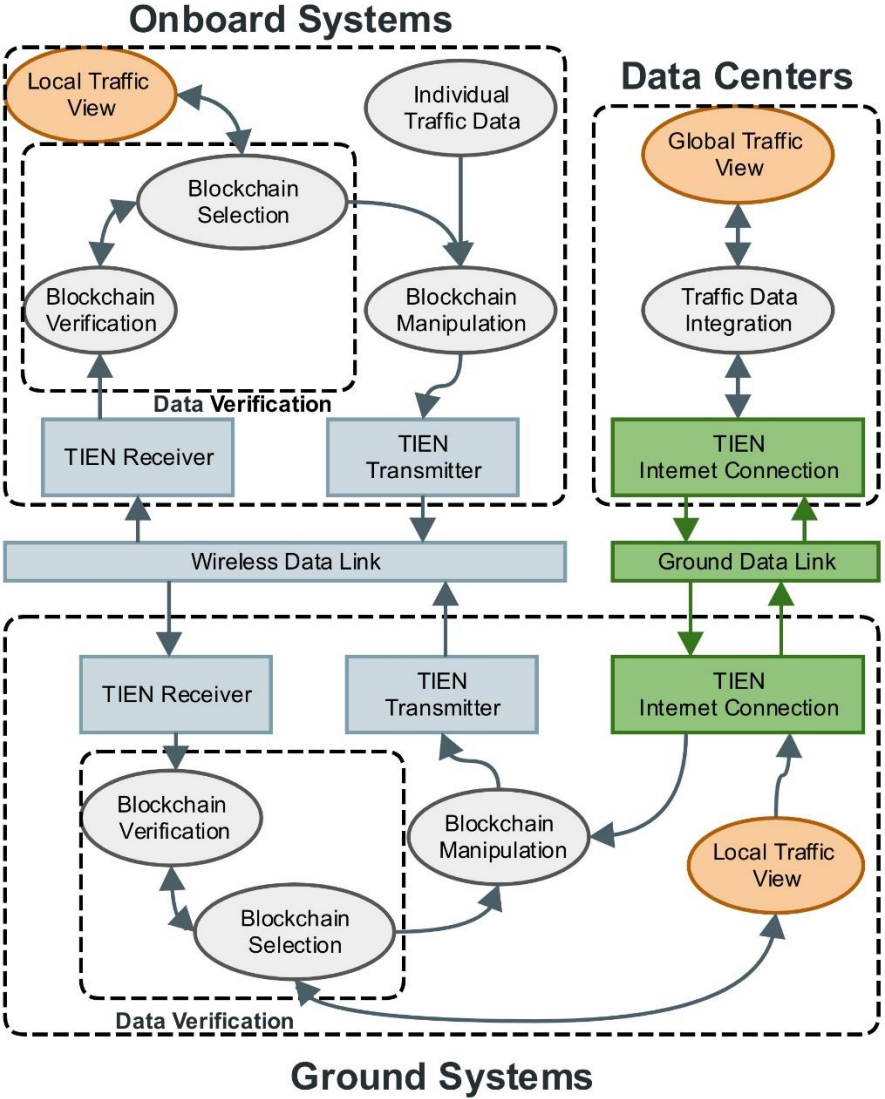
Traffic Information Exchange Network (TIEN) & Blockchain

What is blockchain? – Hash Function 101

- Properties of Hash Function
 - **Pseudo-random**: A specific “output” according to the input
 - **No inverse function**: Extremely hard to find a reversed function
 - **Uniqueness**: Almost no two sets of input have the same output
- Example: (SHA3-256 hash function)
 - $H(\text{'TIEN'}) =$
hex'ac9b93c166f5c8661908bcbe1eaca1f67cec943f82b080a75d13cb4f47d66f39'
 - $H(\text{'TIEN.'}) =$
hex'b96c3cc063177621792829a6a4d2a3ac0d93e53abed452976d82f67929918476'



Framework

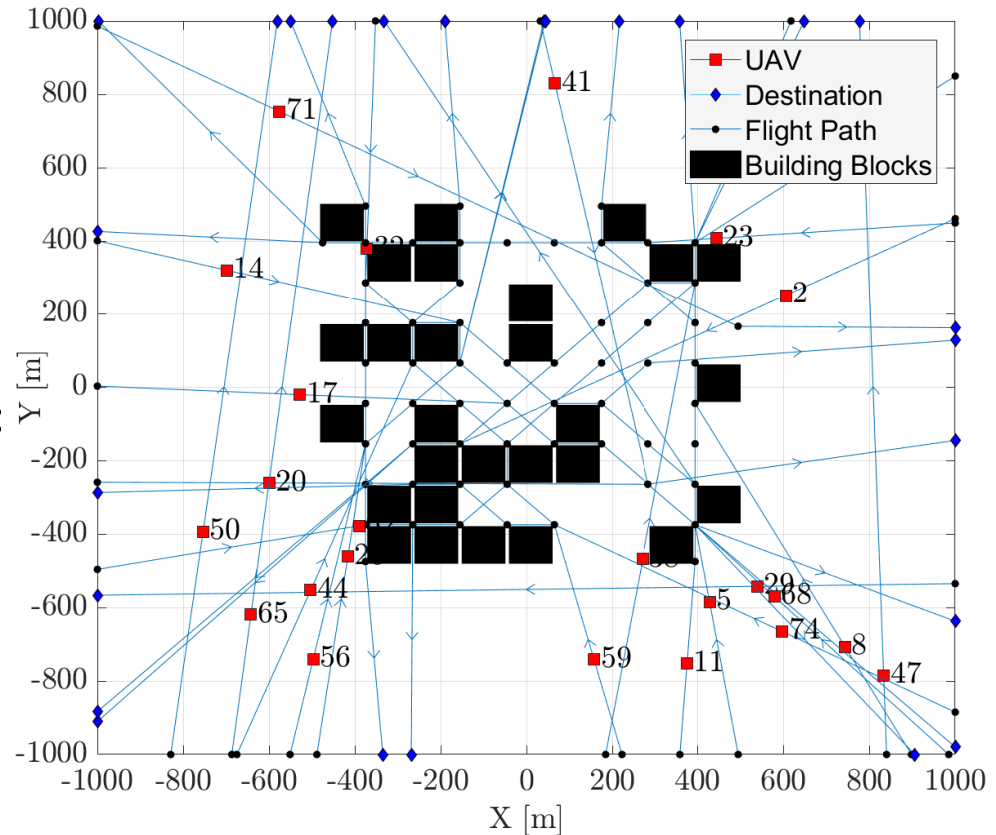


Subscribers

- Ground Communication
- Air Communication
- Provided Information

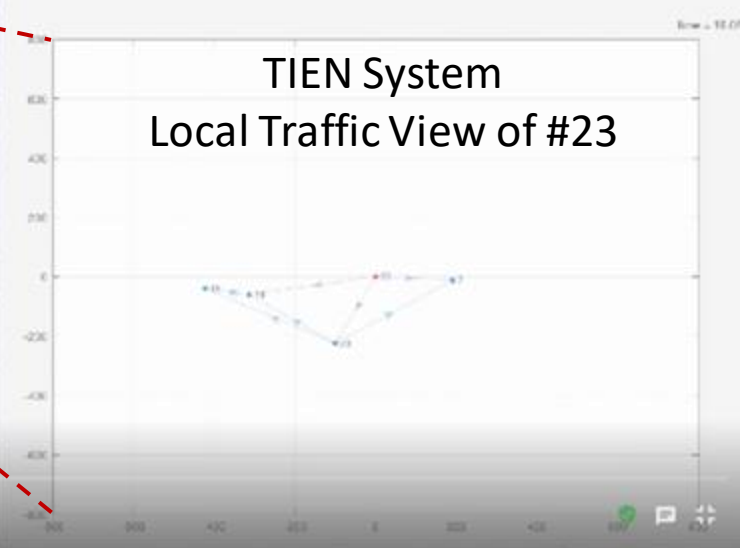
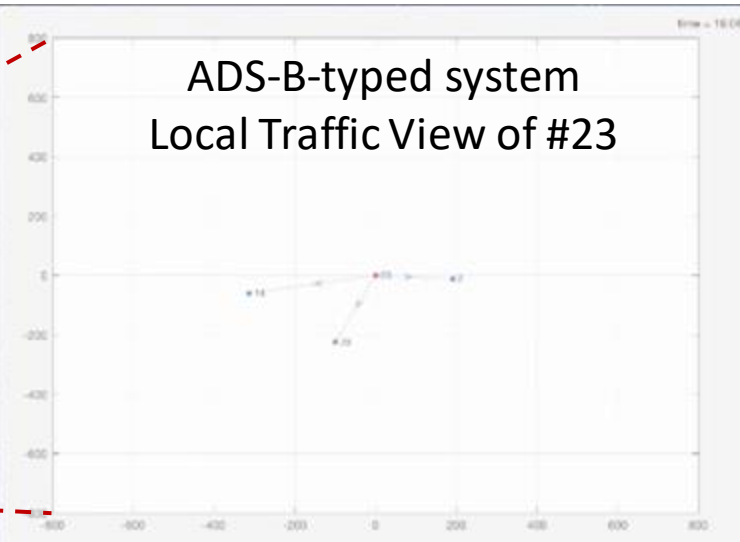
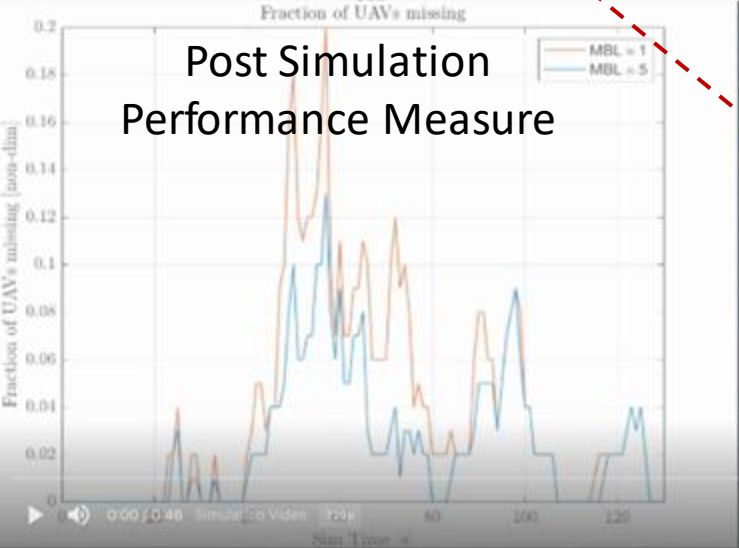
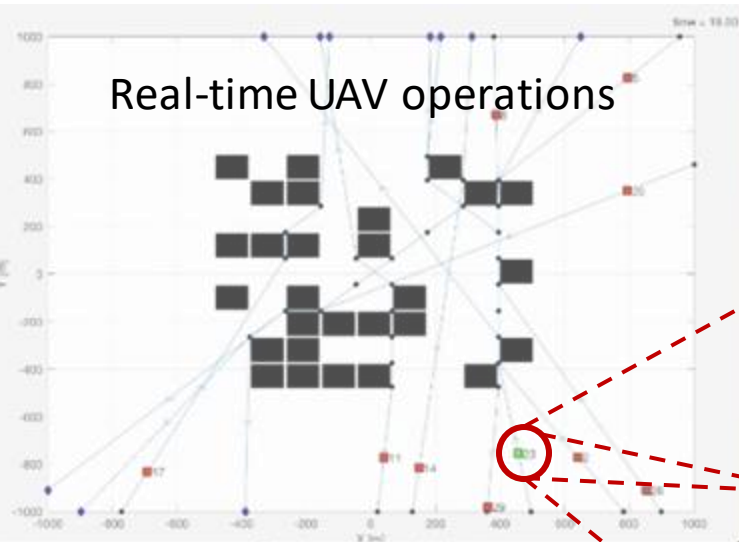
Simulation Setup

- Goal: Proof-of-concept
 - Evaluate properties of the blockchain-inspired data transmission mechanism
 - The ground systems and data centers are not modeled in the simulation yet
- Environment:
 - A virtual world
 - A virtual city
 - Building Blocks
- TIEN and UAV Operation Assumptions:
 - No collision avoidance
 - Start and finish points of a flight are at the edges of virtual world
 - Only deploy onboard systems
 - Data transmission rate is 110 kbps; average block size is roughly 800 bits
- ADS-B can be regarded as a special case of the data transmission with only 1 block

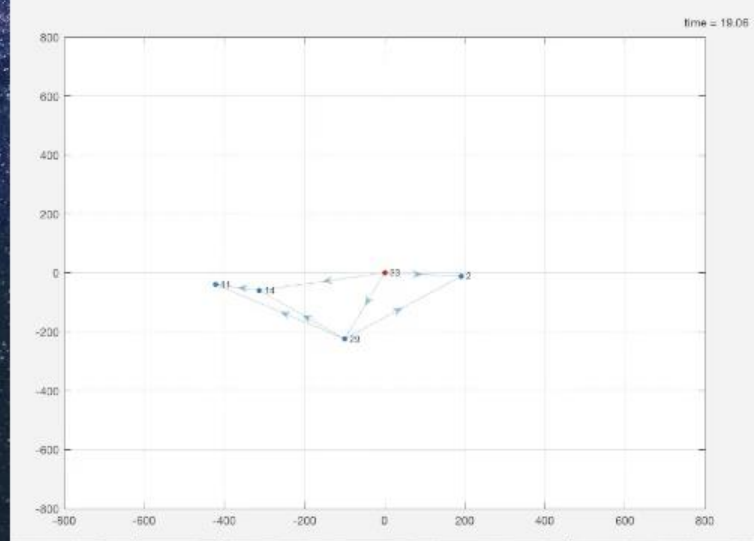
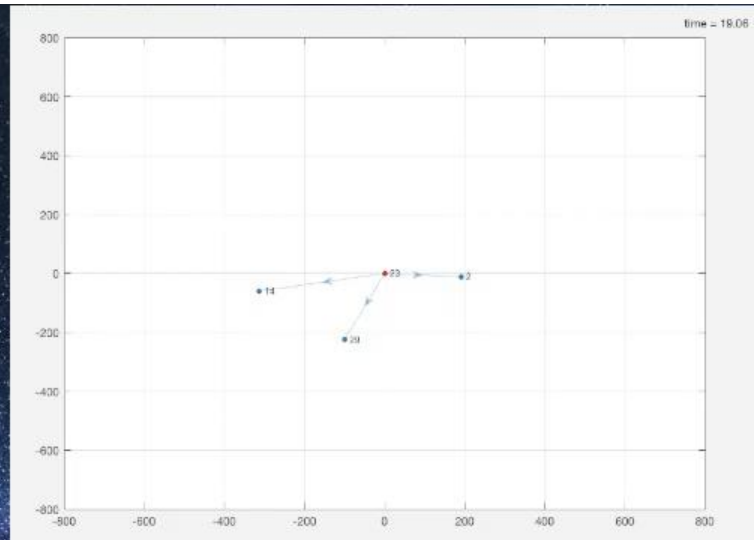
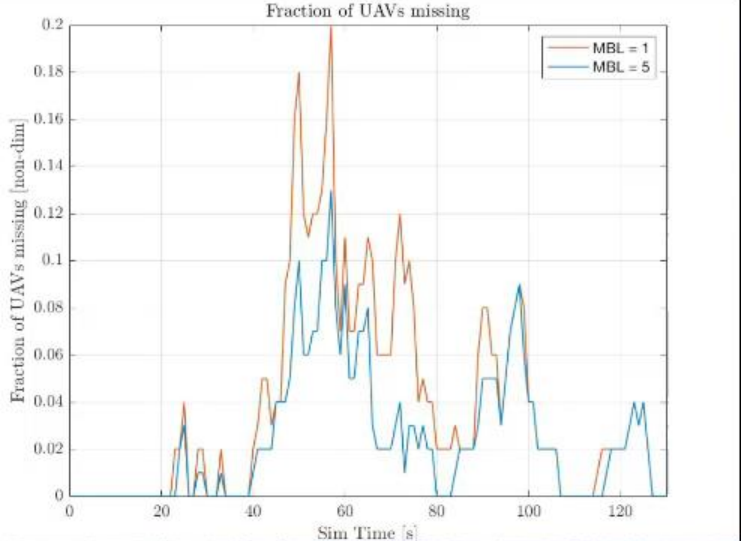
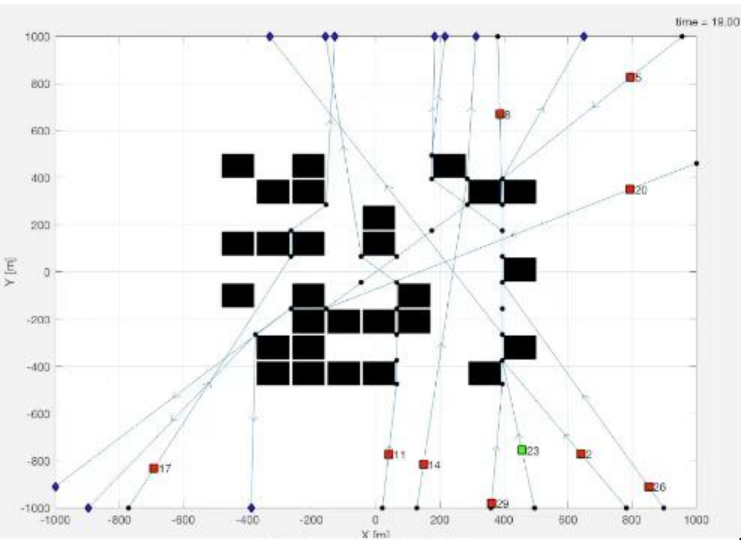


Snapshot of the simulation with 25 UAV operations

Simulation Demonstration

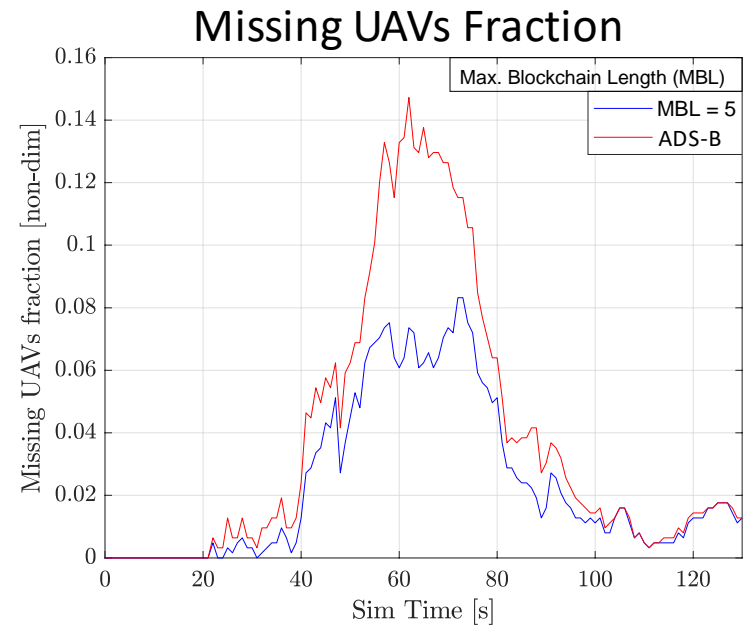


Simulation Demonstration



Results and Discussion

- Randomly generated:
 - City layout
 - UAV flight plan and OD pair
 - UAV cruise speed
- Study the impacts of:
 - Number of UAVs in the simulation
 - Broadcasting Frequency
 - Maximum number of relayed blocks
- Missing UAVs Fraction:
 - Measure the fraction of UAVs which are in the broadcasting range but are not seen by others
 - TIEN has lower Missing UAVs Fraction value throughout the simulation than ADS-B-like system
- Effective broadcasting range:
 - UAVs with TIEN can broadcast their position further than its broadcasting range
 - We observed that the effective broadcasting range can be as high as 5 times the broadcasting range
 - The broadcasting range can be reduced to reduce power consumption while maintaining good coverage
- System scalability
 - TIEN is a distributed system, so its performance increases with higher number of UAVs, which is verified by the simulation results



Conclusion & Future Work

- Conclusions:
 - UAV-TIEN system is a data transmission system to provide free and secured traffic information for everyone
 - Simulation results confirm the robustness and scalability of TIEN system in urban areas with dense traffic environment
- Future Work
 - Prototype TIEN system and test its performances in the real world.
 - Investigate how ground system affects TIEN onboard system performance and qualities of the global traffic view
 - Select a case study city, such as Washington D.C., Chicago, Manhattan
 - Investigate ground system deployment strategies
 - Demonstrate the robustness against the several types of cyber-attacks

NASA University Student Research Challenge Competition

- This project has won the NASA University Student Research Challenge (USRC) proposal competition
 - This project gets funding from NASA to build and test the prototyping system.
 - Per the proposal requirements, one third of the directed cost has to be raised through crowdfunding campaign.
- Learn more about this project or subscribe for the future updates
 - <https://goo.gl/DWks9L>



Backup slides

Simulation Setup

Parameter	Type of Variable	Values	Parameter	Type of Variable	Values
Virtual World & Virtual City			Onboard System		
Boundary	Deterministic	2 km (1.24 mile)	Maximum Blockchain Length	Deterministic	(1, 5, 10)
City Boundary	Deterministic	1 km (0.62 mile)	Broadcasting Frequency	Deterministic	(1, 2) Hz
Block Boundary	Deterministic	100 m (328 ft)	Broadcasting Range	Deterministic	400 m (1312 ft)
Block has buildings	Binomial	0.4	Data Transmission Rate	Deterministic	110 kbps
UAV			<ul style="list-style-type: none"> Investigate the impacts from the following parameters <ul style="list-style-type: none"> Maximum Blockchain Length (MBL) Broadcasting Frequency Number of UAVs (25, 50, 100) Setting with 1 MBL and 1 Hz broadcasting frequency can be regarded as an ADS-B type system 		
Origin	Uniform				
Destination	Uniform				
Cruise Speed	Gaussian	μ : 70 kmh, σ : 5 kmh (μ : 43 mph, σ : 3 mph)			

System Performance Metrics

- Weighted Position Error (WPE):

$$WPE = \frac{1}{N} \sum_{i=1}^N \left(\frac{1}{N_i} \sum_{j=1}^{N_i} \sum_t \frac{\overbrace{\|x_j(t) - x_j^*(t)\|}^{\text{Position Errors}}}{\underbrace{d_{ij}(t)}_{\text{Relative Distance}}} \right)$$

- Weighted Data Age (WDA):

$$WDA = \frac{1}{N} \sum_{i=1}^N \left(\frac{1}{N_i} \sum_{j=1}^{N_i} \sum_t \frac{\overbrace{\|t - T_j^{i0}(t)\|}^{\text{Data age}}}{d_{ij}(t)} \right)$$

- Missing UAV Fraction (η):

$$\eta(t) = \frac{1}{N} \sum_{i=1}^N \frac{N_{in}^i(t)}{N_{br}^i(t)}$$

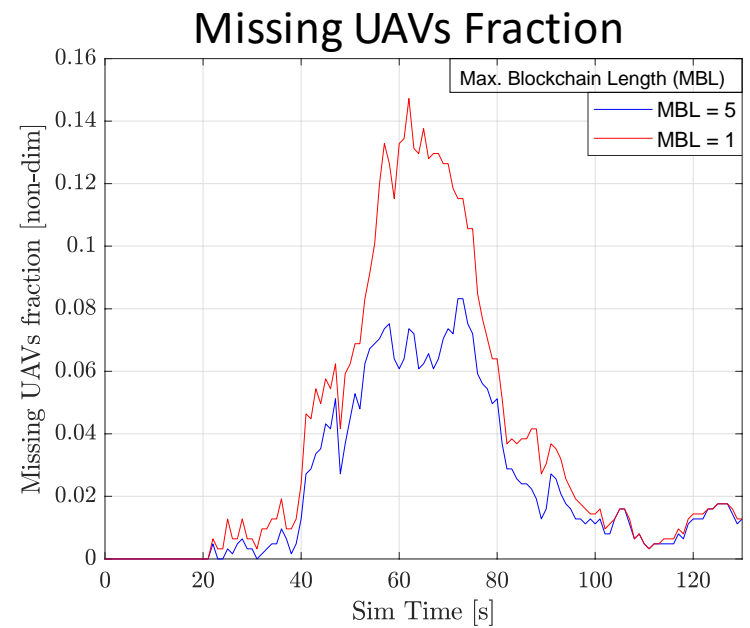
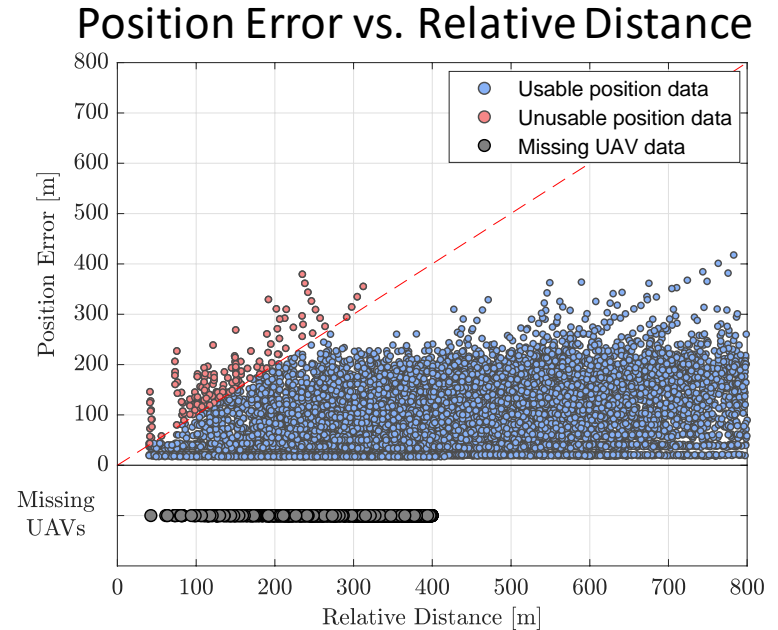
of invisible UAVs
of UAVs in the broadcasting range

- Effective Broadcast Range (BR_{eff}):

$$BR_{eff} = \frac{1}{BR} \max_{i,j,t} \left\{ d_{ij}(t) \times \underbrace{I_{\epsilon_{ij}(t) \leq \epsilon_{th}}}_{\text{Check whether the position error is within the threshold}} \right\}$$

Simulation Results & Discussion

- Simulation settings for the results shown on left:
 - 25 UAVs
 - 1 Hz Broadcasting Frequency
 - (1, 5) MBL
- Position Error vs. Relative Distance:
 - A data point is unusable if the position error is more than the relative distance.
 - Most of data points are usable.
 - There are more missing UAVs at the edge of broadcasting range.
- Missing UAVs Fraction:
 - ADS-B type system has 14~15% missing UAVs fraction.
 - The MBL can reduce the missing UAV fraction to 8~9%.



Simulation Results & Discussion

- Statistical Analysis:
 - Linear cell effect model w/o interaction terms
- Impacts of MBL
 - Improve the accuracy of traffic data (Decrease the WPE)
 - Decrease the missing UAV fraction
 - Increase effective broadcasting range
- Impacts of BF
 - Improve the accuracy of traffic data
 - Decrease the effective broadcasting range.
 - TIEN broadcast the latest received blockchain; this hurts the information propagation when number of received blockchain increased.
- Impacts of number of UAVs
 - This has not significant effects on WPE and WDA
 - Increase the effective broadcasting range.
 - TIEN system has higher chances to find a relay to propagate information

Simulation Scenario Counting

		nUAVs & Broadcasting Frequency (BF)					
		1 Hz			2 Hz		
		25	50	100	25	50	100
MBL	1	19	18	5	22	15	2
	5	19	14	6	19	7	3
	10	14	18	10	14	15	2

Linear Regression Analysis Results

	WPE	WDA	η_{avg}	BR_{eff}
Intercept	0.3329	0.0152	0.0423	1.1553
MBL = 5	-0.0229	-0.007	-0.0157	1.8878
MBL = 10	-0.0408	-0.0016	-0.0209	2.3690
BF = 2 Hz	-0.0737	-0.0039	0.0133	-0.1983
nUAVs = 50	NS	NS	NS	0.5692
nUAVs = 100	NS	NS	NS	1.0453